

19 Μαΐου

Φροντιστήριο

SVD - Polar

1 Πολική διάσπαση $A = \begin{bmatrix} 1,3 & -0,375 \\ 0,75 & 0,65 \end{bmatrix}$

$$A = Q|A|$$

θεωρία

$$|A| = (A^T A)^{1/2}$$

ρίζα

$$Q = \text{ορθώγωνος}, Q^T = Q^{-1}$$

(στρογγύ)

$$\text{και: } Q = (A^T)^{-1} \cdot |A|$$

Πρώτα: $A^T A = \begin{bmatrix} 1,3 & 0,75 \\ -0,375 & 0,65 \end{bmatrix} \begin{bmatrix} 1,3 & -0,375 \\ 0,75 & 0,65 \end{bmatrix}$

=

$$\begin{bmatrix} 2,25 & 0 \\ 0 & 0,563 \end{bmatrix} = T$$

$$|A| = T^{1/2} = \begin{bmatrix} \sqrt{2,25} & 0 \\ 0 & \sqrt{0,563} \end{bmatrix} = \begin{bmatrix} 1,5 & 0 \\ 0 & 0,751 \end{bmatrix}$$

Q: $(A^T)^{-1} \cdot |A| = \begin{bmatrix} 1,3 & 0,75 \\ -0,375 & 0,65 \end{bmatrix}^{-1} \cdot \begin{bmatrix} 1,5 & 0 \\ 0 & 0,75 \end{bmatrix}$

$$= \begin{bmatrix} 0,577 & -0,666 \\ 0,333 & 1,15 \end{bmatrix} \cdot \begin{bmatrix} 1,5 & 0 \\ 0 & 0,75 \end{bmatrix} =$$

$$\begin{bmatrix} 0,866 & -0,5 \\ 0,5 & 0,866 \end{bmatrix} = Q$$

ορθογώνιος ($Q^{-1} = Q^T$) $R =$ στροφής

$$Q = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \curvearrowright \theta$$

$$\text{Εδώ } \theta = \frac{\pi}{6} \curvearrowright$$

$$A = \begin{bmatrix} 0,866 & -0,5 \\ 0,5 & 0,866 \end{bmatrix} \cdot \begin{bmatrix} 1,5 & 0 \\ 0 & 0,751 \end{bmatrix}$$

σφολογήσι 30° ↗

πληροφόρησε ↗

② SVD : "διαγωνιοποίηση"

$$A = U \Sigma V^T$$

↓ ↘
ορθογώνιοι

$$A = \begin{bmatrix} 1 & 2 & -1 & 1 \\ -1 & -2 & 1 & 3 \end{bmatrix}$$

(2x4)

$$\text{rank}(A) = 2$$

$$\Sigma = \text{rank } 2$$

U:

$$AA^T = \begin{bmatrix} 7 & -3 \\ -3 & 15 \end{bmatrix}$$

(2x4) · (4x2)

Ιδιότητες :

| | |
|------------------|-----------------------------------|
| $\lambda_1 = 16$ | $\rightarrow \sigma_1 = 4$ |
| $\lambda_2 = 6$ | $\rightarrow \sigma_2 = \sqrt{6}$ |

$$\vec{u} = \begin{pmatrix} -1 \\ 3 \end{pmatrix} \quad \vec{v} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \quad (\vec{u} \perp \vec{v})$$

ΚΑΝΟΝΙΚΟ ΠΑΙΧΗΤΗ :

$$\vec{u} = \begin{pmatrix} -\frac{1}{\sqrt{10}} \\ \frac{3}{\sqrt{10}} \end{pmatrix} \quad \vec{v} = \begin{pmatrix} \frac{3}{\sqrt{10}} \\ \frac{1}{\sqrt{10}} \end{pmatrix}$$

$$U = \begin{bmatrix} -\frac{1}{\sqrt{10}} & \frac{3}{\sqrt{10}} \\ \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \end{bmatrix}$$

Σ : 2×4 , $\text{rank}(\Sigma) = 2$, $\sigma_1 = 4$
 $\sigma_2 = \sqrt{6}$

$$\begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & \sqrt{6} & 0 & 0 \end{bmatrix}$$

V : από τον $A^T A = 4 \times 4$

$4 \times 2 \quad 2 \times 4$

$$= \begin{bmatrix} 2 & 4 & -2 & -2 \\ 4 & 8 & -4 & -4 \\ -2 & -4 & 2 & 2 \\ -2 & -4 & 2 & 10 \end{bmatrix}$$

$\text{rank} = 2$

4 ιδιοτιμές: $16, 6, 0, 0 \rightarrow$ διπλή ιδιοτιμή

Ιδιοδιανύσματα:

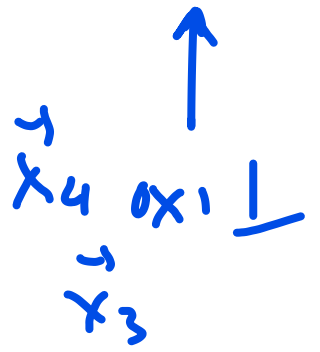
$$\vec{x}_1 = \begin{pmatrix} -1 \\ -2 \\ 1 \\ 2 \end{pmatrix}$$

$$\vec{x}_2 = \begin{pmatrix} 1 \\ 2 \\ -1 \\ 3 \end{pmatrix}$$

$$\vec{x}_3 = \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\vec{x}_4 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

Θα κάνω Gram-Schmidt
στο \vec{x}_4



$$\hat{x}_4 = x_4 - \frac{\langle x_3, x_4 \rangle}{\|x_3\|^2} \vec{x}_3 =$$

$$\begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} - \frac{-2}{5} \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \hat{x}_4 \\ 1/5 \\ 2/5 \\ 1 \\ 0 \end{pmatrix}$$

Κανονικοποίηση στα:

$$\vec{x}_1, \vec{x}_2, \vec{x}_3, \hat{x}_4$$

Βάζω σε στήλες στον V :

$$V = \begin{bmatrix} -\frac{1}{\sqrt{10}} & \frac{1}{\sqrt{15}} & -\frac{2}{\sqrt{15}} & \frac{1}{\sqrt{30}} \\ -\frac{2}{\sqrt{10}} & \frac{2}{\sqrt{15}} & \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{30}} \\ \frac{1}{\sqrt{10}} & -\frac{1}{\sqrt{15}} & 0 & \frac{5}{\sqrt{30}} \\ \frac{2}{\sqrt{10}} & \frac{3}{\sqrt{15}} & 6 & 0 \end{bmatrix}$$

$$A = U \Sigma V^T$$

Σίνδεση SVD - Polar

$$A = Q|A| = \underbrace{(UV)}_Q \cdot \underbrace{(V \Sigma V^T)}_{|A|}$$

$$\text{AV} \\ A = U \Sigma V^T$$

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Πολικη:

$$A = \begin{bmatrix} \frac{10}{\sqrt{10}} & \frac{6}{\sqrt{10}} \\ 0 & \frac{8}{\sqrt{10}} \end{bmatrix}$$

Φορμαζικό θεώρημα:

$$A^T A = \begin{bmatrix} 10 & 6 \\ 6 & 10 \end{bmatrix}$$

εija?

Ιδιοτιμές: 4, 16

$$|A| = (A^T A)^{1/2}$$

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}, \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

Διαγωνιοποίηση.

$$A^T A = P D P^{-1} = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 4 & 0 \\ 0 & 16 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

Απο. $(A^T A)^{1/2} = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$

πράξεις $\Rightarrow (A^T A)^{1/2} = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} = |A|$

$A = Q \cdot |A|$ ή $A = |A| \cdot U$

\hookrightarrow ή $Q = A \cdot |A|^{-1} = \begin{bmatrix} \frac{10}{\sqrt{10}} & \frac{6}{\sqrt{10}} \\ 0 & \frac{8}{\sqrt{10}} \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}^{-1}$

$Q = (A^T)^{-1} \cdot |A|$

$= \dots \begin{bmatrix} \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \\ -\frac{1}{\sqrt{10}} & \frac{3}{\sqrt{10}} \end{bmatrix} Q$

πίνακας στρεφής

$\cos \theta = \frac{3}{\sqrt{10}}$

$\sin \theta = -\frac{1}{\sqrt{10}}$



$18,5^\circ$ στρουγί

$$A = Q \cdot |A|$$

4) $A = \begin{bmatrix} 3 & -3 \\ -3 & -5 \end{bmatrix}$ $\lambda_1 = -6$
 $\lambda_2 = k$

a) k ?

b) A^{10} ?

a) $\text{trace}(A) = \sum \lambda_i$

$$\Rightarrow 3 - 5 = -6 + k \Rightarrow$$

$$k = 4$$

b) ιδιοδιανύσματα

$$A\vec{u} = -6\vec{u} \rightarrow \dots$$

$$\vec{u} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}, A\vec{v} = 4\vec{v} \rightarrow \dots \vec{v} = \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

ΔΙΑΓΩΝΙΣΜΟΣ:

$$A = P \cdot D \cdot P^{-1} =$$

$$\begin{bmatrix} 1 & -3 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} -6 & 6 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} \frac{1}{10} & \frac{3}{10} \\ -\frac{3}{10} & \frac{1}{10} \end{bmatrix} \Rightarrow$$

$$A^{10} = P \cdot \begin{bmatrix} (-6)^{10} & 0 \\ 0 & 4^{10} \end{bmatrix} P^{-1} \dots$$

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$$A = \begin{bmatrix} 0,4 & -0,3 \\ 0,4 & 1,2 \end{bmatrix}$$

α) διαγωνοποιείται?

β) $\lim_{k \rightarrow \infty} A^k = ?$

Ιδιοτιμές:

$$\begin{vmatrix} 0,4 - \lambda & -0,3 \\ 0,4 & 1,2 - \lambda \end{vmatrix} = 0$$

$$\Rightarrow (0,4-\lambda)(1,2-\lambda)+0,12=0 \Rightarrow$$

$$\lambda=1, \lambda=0,6$$

Diagonalisasi: $\vec{u} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ $\vec{v} = \begin{pmatrix} -3 \\ 2 \end{pmatrix}$

NAI -

$$A = \begin{bmatrix} -1 & -3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0,6 \end{bmatrix} \begin{bmatrix} -1 & -3 \\ 2 & 2 \end{bmatrix}^{-1}$$

$$e) A^k = \begin{bmatrix} -1 & -3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1^k & 0 \\ 0 & 0,6^k \end{bmatrix} \cdot \begin{bmatrix} \frac{2}{4} & \frac{3}{4} \\ \frac{-2}{4} & \frac{-1}{4} \end{bmatrix}$$

Apa limit $\lim_{k \rightarrow \infty} P \begin{bmatrix} 1^k & 0 \\ 0 & 0,6^k \end{bmatrix} P^{-1} =$

$$P \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} P^{-1} =$$

$$\begin{bmatrix} -1 & -3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -\frac{2}{4} & \frac{3}{4} \\ -\frac{2}{4} & -\frac{1}{4} \end{bmatrix} =$$

$$A^K = \begin{bmatrix} -\frac{1}{2} & -\frac{3}{4} \\ 1 & \frac{3}{2} \end{bmatrix}$$

$K \rightarrow +\infty$



