

# MSc MATHS ECON - TUTORIAL 2

## Difference Equations and Lag Operators

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# First-order Difference Equations

The general form is:

$$b_1 y_t + b_0 y_{t-1} = g(t)$$

where  $g(t)$  is a known function. The solution of the homogeneous equations  $b_1 y_t + b_0 y_{t-1} = 0$  is:

$$y_t^h = c(-\lambda)^t$$

where  $c$  is an arbitrary constant and  $\lambda = \frac{b_0}{b_1}$ .

Use the method of undetermined coefficients to find a particular solution  $\bar{y}_t$ . The general solution equals the sum of the solutions of the homogeneous and the non-homogeneous equation (the particular solution):

$$y_t = y_t^h + \bar{y}_t = c(-\lambda)^t + \bar{y}_t$$

In order to determine the arbitrary constant we need one additional condition:

$$y_t = y^* \quad \text{for} \quad t = t^*$$

where  $y^*$  and  $t^*$  are known values.

## Polynomial guess

Solve  $y_{t+1} - 5y_t = 3t + 2$  subject to  $y_0 = 0$

We will start by solving the homogeneous equation  $y_{t+1} - 5y_t = 0$

Let non-trivial solution  $y_t = \lambda^t \neq 0$  and substitute into the homogeneous equation:

$$y_{t+1} - 5y_t = 0 \Rightarrow \lambda^{t+1} - 5\lambda^t = 0 \Leftrightarrow$$

$$\lambda^t(\lambda - 5) = 0 \Leftrightarrow \lambda = 5$$

Therefore, the solution of the homogeneous equation is:

$$y_t^h = c\lambda^t = c5^t$$

Next, we will solve the non-homogeneous equation by trying a solution in the form of a first order polynomial guess function in  $t$ :

$$y_t = at + \beta, \quad y_{t+1} = a(t + 1) + \beta$$

and will substitute for  $y_t$  and  $y_{t+1}$  into the original equation leaving the RHS unchanged:

# Polynomial guess

$$y_{t+1} - 5y_t = 3t + 2 \Rightarrow a(t+1) + \beta - 5(at + \beta) = 3t + 2 \Leftrightarrow$$

$$at + a + \beta - 5at - 5\beta = 3t + 2 \Leftrightarrow$$

$$-4at - 4\beta + a = 3t + 2$$

Equating coefficients on both sides yields a linear system in two unknown parameters (the undetermined coefficients):

$$\left\{ \begin{array}{l} -4a = 3 \\ -4\beta + a = 2 \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} a = -\frac{3}{4} \\ \beta = -\frac{11}{16} \end{array} \right\}$$

Therefore, the solution of the non-homogeneous equation is:

$$\bar{y}_t = -\frac{3}{4}t - \frac{11}{16}$$

The general solution equals the sum of the solution of the homogeneous and the non-homogeneous equation.

# Polynomial guess

$$y_t = y_t^h + \bar{y}_t \Rightarrow$$
$$y_t = c5^t - \frac{3}{4}t - \frac{11}{16} \quad \forall t$$

We may use the initial condition in order to determine the arbitrary constant  $c$  in the general solution:

$$0 = y_0 = c5^0 - \frac{3}{4}0 - \frac{11}{16} \Leftrightarrow$$
$$c = \frac{11}{16}$$

Therefore, the general solution equals:

$$y_t = \frac{11}{16}5^t - \frac{3}{4}t - \frac{11}{16} \quad \forall t$$

Since the characteristic root is  $\lambda = 5 > 0$  and  $|\lambda| > 1$ ; the movement will be monotonically divergent (from the long run equilibrium) as  $t \rightarrow \infty$ .

# Exponential guess

Solve  $y_t - 3y_{t-1} = 4^t$  subject to  $y_0 = 0$ .

We will start by solving the homogeneous equation  $y_t - 3y_{t-1} = 0$ .

Let non-trivial solution  $y_t = \lambda^t \neq 0$  and substitute into the homogeneous equation:

$$y_t - 3y_{t-1} = 0 \Rightarrow \lambda^t - 3\lambda^{t-1} = 0 \Leftrightarrow$$

$$\lambda^{t-1}(\lambda - 3) = 0 \Leftrightarrow \lambda = 3$$

Therefore, the solution of the homogeneous equation is:

$$y_t^h = c\lambda^t = c3^t$$

Since the characteristic root is  $\lambda = 3 > 0$  and  $|\lambda| > 1$ ; the movement will be monotonically divergent as  $t \rightarrow \infty$ .

Next, we will solve the non-homogeneous equation by trying a solution in the form of a first order exponential guess function in t:

$$y_t = a4^t, \quad y_{t-1} = a4^{t-1}$$

# Exponential guess

Substitute for  $y_t$  and  $y_{t-1}$  into the original equation leaving the RHS unchanged:

$$\begin{aligned}y_t - 3y_{t-1} &= 4^t \Rightarrow a4^t - 3a4^{t-1} = 4^t \Leftrightarrow \\(a - 3a4^{-1})4^t &= 4^t \Leftrightarrow a\left(1 - \frac{3}{4}\right)4^t = 4^t \Leftrightarrow \\a\frac{1}{4}4^t &= 4^t\end{aligned}$$

Equating coefficients on both sides allows us to determine  $a$ :

$$\frac{a}{4} = 1 \Leftrightarrow a = 4$$

Therefore, the solution of the non-homogeneous equation is:

$$\bar{y}_t = 44^t = 4^{t+1}$$

# Exponential guess

The general solution equals the sum of the solution of the homogeneous and the non-homogeneous equation.

$$y_t = y_t^h + \bar{y}_t \Rightarrow$$
$$y_t = c3^t + 4^{t+1} \quad \forall t$$

We may use the initial condition in order to determine the arbitrary constant  $c$  in the general solution:

$$0 = y_0 = c3^0 + 4 \Leftrightarrow$$

$$c = -4$$

Therefore, the general solution equals:

$$y_t = -43^t + 4^{t+1} \Leftrightarrow$$

$$y_t = 4(4^t - 3^t) \quad \forall t$$



# Trigonometric Formulas

$$\cos(\omega t \pm \omega) = \cos\omega t \cos\omega \mp \sin\omega t \sin\omega$$

$$\sin(\omega t \pm \omega) = \sin\omega t \cos\omega \pm \sin\omega \cos\omega t$$

## Trigonometric guess

Solve  $y_{t+1} + \frac{\sqrt{2}}{2}y_t = \cos(\frac{\pi t}{4})$  subject to  $y_0 = 0$ .

We will start by solving the homogeneous equation

$$y_{t+1} + \frac{\sqrt{2}}{2}y_t = 0.$$

Let non-trivial solution  $y_t = \lambda^t \neq 0$  and substitute into the homogeneous equation:

$$y_{t+1} + \frac{\sqrt{2}}{2}y_t = 0 \Rightarrow \lambda^{t+1} + \frac{\sqrt{2}}{2}\lambda^t = 0 \Leftrightarrow \lambda^t(\lambda + \frac{\sqrt{2}}{2}) = 0 \Leftrightarrow \lambda = -\frac{\sqrt{2}}{2}$$

Therefore, the solution of the homogeneous equation is:

$$y_t^h = c\lambda^t = c(-\frac{\sqrt{2}}{2})^t$$

Next, we will solve the non-homogeneous equation by trying a solution in the form of a first order sinusoidal guess function in  $t$ :

$$y_t = a \cos(\omega t) + \beta \sin(\omega t)$$

$$y_{t+1} = a \cos(\omega(t+1)) + \beta \sin(\omega(t+1))$$

# Trigonometric guess

$$y_{t+1} = a(\cos(\omega t)\cos\omega - \sin(\omega t)\sin\omega) + \beta(\sin(\omega t)\cos\omega + \sin\omega \cos(\omega t))$$
$$= a \cos(\omega t)\cos\omega - a \sin(\omega t)\sin\omega + \beta \sin(\omega t)\cos\omega + \beta \sin\omega \cos(\omega t)$$

and will substitute for  $y_t$  and  $y_{t+1}$  into the original equation leaving the RHS unchanged:

$$y_{t+1} + \frac{\sqrt{2}}{2}y_t = \cos\left(\frac{\pi t}{4}\right)$$

$$a \cos(\omega t)\cos\omega - a \sin(\omega t)\sin\omega + \beta \sin(\omega t)\cos\omega + \beta \sin\omega \cos(\omega t) + \frac{\sqrt{2}}{2}[a \cos(\omega t) + \beta \sin(\omega t)] = \cos\left(\frac{\pi t}{4}\right) \Leftrightarrow$$

$$\left(a \cos\omega + \beta \sin\omega + a\frac{\sqrt{2}}{2}\right)\cos(\omega t) + \left(-a \sin\omega + \beta \cos\omega + \beta\frac{\sqrt{2}}{2}\right)\sin(\omega t) = \cos\left(\frac{\pi t}{4}\right)$$

# Trigonometric guess

Equating coefficients and angles on both sides yields:

$$\left\{ \begin{array}{l} \omega = \frac{\pi}{4} \\ a \cos \omega + \beta \sin \omega + a \frac{\sqrt{2}}{2} = 1 \\ \beta \cos \omega - a \sin \omega + \beta \frac{\sqrt{2}}{2} = 0 \end{array} \right\} \Leftrightarrow$$
$$\left\{ \begin{array}{l} \omega = \frac{\pi}{4} \\ a \cos \frac{\pi}{4} + \beta \sin \frac{\pi}{4} + a \frac{\sqrt{2}}{2} = 1 \\ \beta \cos \frac{\pi}{4} - a \sin \frac{\pi}{4} + \beta \frac{\sqrt{2}}{2} = 0 \end{array} \right\} \Leftrightarrow$$
$$\left\{ \begin{array}{l} \omega = \frac{\pi}{4} \\ \frac{a}{\sqrt{2}} + \frac{\beta}{\sqrt{2}} + a \frac{\sqrt{2}}{2} = 1 \\ \frac{\beta}{\sqrt{2}} - \frac{a}{\sqrt{2}} + \beta \frac{\sqrt{2}}{2} = 0 \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \omega = \frac{\pi}{4} \\ a = \frac{2\sqrt{2}}{5} \\ \beta = \frac{\sqrt{2}}{5} \end{array} \right\}$$

## Trigonometric guess

Therefore, the solution of the non-homogeneous equation is:

$$\bar{y}_t = \frac{\sqrt{2}}{5} \left( 2 \cos\left(\frac{\pi}{4}t\right) + \sin\left(\frac{\pi}{4}t\right) \right)$$

So, the general solution equals:

$$y_t = y_t^h + \bar{y}_t \Rightarrow$$

$$y_t = c \left(-\frac{\sqrt{2}}{2}\right)^t + \frac{\sqrt{2}}{5} \left( 2 \cos\left(\frac{\pi}{4}t\right) + \sin\left(\frac{\pi}{4}t\right) \right) \quad \forall t$$

We may use the initial condition in order to determine the arbitrary constant  $c$  in the general solution:

$$0 = y_0 = c \left(-\frac{\sqrt{2}}{2}\right)^0 + \frac{\sqrt{2}}{5} \left( 2 \cos\left(\frac{\pi}{4}0\right) + \sin\left(\frac{\pi}{4}0\right) \right) \Leftrightarrow$$

$$0 = c + \frac{2\sqrt{2}}{5} \Leftrightarrow c = -\frac{2\sqrt{2}}{5}$$

Therefore, the general solution equal:

$$y_t = -\frac{2\sqrt{2}}{5}\left(-\frac{\sqrt{2}}{2}\right)^t + \frac{\sqrt{2}}{5}\left(2\cos\left(\frac{\pi}{4}t\right) + \sin\left(\frac{\pi}{4}t\right)\right) \quad \forall t$$

## Second Order Difference Equations

Solve  $y_{t+2} - 4y_{t+1} + 3y_t = 5^t$  subject to  $y_0 = 1$  and  $y_1 = 2$ .

Firstly consider the homogeneous equation:

$$y_{t+2} - 4y_{t+1} + 3y_t = 0.$$

Its characteristic equation is:

$$\lambda^2 - 4\lambda + 3 = 0$$

$$\lambda^2 + \alpha_1\lambda + \alpha_2 = 0$$

$$\alpha_1 = -4 \quad \alpha_2 = 3$$

The necessary and sufficient conditions for stability, namely:

$$1 + a_1 + a_2 > 0$$

$$1 - a_2 > 0$$

$$1 - a_1 + a_2 > 0$$

are not simultaneously satisfied.

## Discriminant $\Delta > 0$

Moreover, since  $\Delta = 4 > 0$  and the coefficient of the characteristic polynomial alternate in sign, the roots will be positive by Descartes' Theorem. Indeed:

$$\lambda_{1,2} = \frac{4 \pm \sqrt{(-4)^2 - 4 \cdot 1 \cdot 3}}{2 \cdot 1}$$

$$\lambda_1 = 3, \lambda_2 = 1 \quad \lambda_1 \neq \lambda_2 \quad \lambda_1, \lambda_2 \in \mathbb{R}$$

Therefore, the solution of the homogeneous equation is:

$$y_t^h = A_1 \lambda_1^t + A_2 \lambda_2^t = A_1 3^t + A_2$$

Next, consider the non-homogeneous equation

$y_{t+2} - 4y_{t+1} + 3y_t = 5^t$ . Try an exponential guess function.

$$y_t = a5^t, y_{t+1} = a5^{t+1}, y_{t+2} = a5^{t+2}$$

Substituting in the non-homogeneous equation yields:

$$a5^{t+2} - 4a5^{t+1} + 3a5^t = 5^t \Leftrightarrow 25a - 20a + 3a = 1 \Leftrightarrow a = \frac{1}{8}$$



# Discriminant $\Delta > 0$

Therefore:

$$PS : \bar{y}_t = \frac{1}{8}5^t$$

$$GS : y_t = A_1 3^t + A_2 + \frac{1}{8}5^t$$

Moreover:

$$IC1 : y_0 = 1 \Leftrightarrow A_1 3^0 + A_2 + \frac{1}{8}5^0 = 1 \Leftrightarrow A_1 + A_2 = \frac{7}{8}$$

$$IC2 : y_1 = 2 \Leftrightarrow A_1 3^1 + A_2 + \frac{1}{8}5^1 = 2 \Leftrightarrow 3A_1 + A_2 = \frac{11}{8}$$

Solving this linear system for  $A_1$  and  $A_2$  yields:  $A_1 = \frac{1}{4}$ ,  $A_2 = \frac{5}{8}$

Therefore:

$$GS : y_t = \frac{1}{4}3^t + \frac{5}{8} + \frac{1}{8}5^t$$

and  $\lim_{t \rightarrow +\infty} y_t = +\infty$

## Discriminant $\Delta=0$

Solve  $y_{t+2} - 2y_{t+1} + y_t = -6^t + t$  assuming arbitrary initial conditions.

Firstly consider the HE:  $y_{t+2} - 2y_{t+1} + y_t = 0$ . Its characteristic equation is:

$$\lambda^2 - 2\lambda + 1 = 0 \Leftrightarrow (\lambda - 1)^2 = 0$$

Moreover  $\Delta = 0$ , and

$$\lambda_1 = \lambda_2 = 1 \in \text{Re with } m = 2$$

where  $m$  indicates the multiplicity of the real repeated root. Hence, the solution of the homogeneous equation equals:

$$y_t^h = A_1 \lambda_1^t + A_2 t \lambda_2^t = A_1 + A_2 t$$

while the necessary and sufficient conditions for stability, namely:

$$1 + a_1 + a_2 > 0$$

$$1 - a_2 > 0$$

$$1 - a_1 + a_2 > 0$$

are not simultaneously satisfied.

## Discriminant $\Delta=0$

Next consider the non-homogeneous equation:

$$y_{t+2} - 2y_{t+1} + y_t = -6^t + t$$

Let us try a mixed guess function for the non-homogeneous part:

$$y_t^g = (a6^t) + (\beta t + \gamma)$$

$$y_{t+1}^g = (a6^{t+1}) + (\beta(t+1) + \gamma)$$

$$y_{t+2}^g = (a6^{t+2}) + (\beta(t+2) + \gamma)$$

Substituting in the non-homogeneous equation yields:

$$a6^{t+2} + (\beta(t+2) + \gamma) - 2[a6^{t+1} + \beta(t+1) + \gamma] + (a6^t) + (\beta t + \gamma) = -6^t + t$$

$$a6^{t+2} + \beta t + 2\beta + \gamma - 2a6^{t+1} - 2\beta t - 2\beta - 2\gamma + a6^t + \beta t + \gamma = -6^t + t$$

$$25a6^t = -6^t + t$$

Equating coefficients implies that  $25a = -1 \Leftrightarrow a = -\frac{1}{25}$ , but  $\beta$  and  $\gamma$  remain undetermined.

# Discriminant $\Delta=0$

Try out an alternative guess function  $y_t^{g2}$  (multiplying the undetermined part of  $y_t^g$  by  $t$ ):

$$y_t^{g2} = (a6^t) + (\beta t^2 + \gamma t)$$

$$y_{t+1}^{g2} = (a6^{t+1}) + (\beta(t+1)^2 + \gamma(t+1))$$

$$y_{t+2}^{g2} = (a6^{t+2}) + (\beta(t+2)^2 + \gamma(t+2))$$

Substituting in the non-homogeneous equation yields:

$$a6^{t+2} + \beta(t+2)^2 + \gamma(t+2) - 2[a6^{t+1} + \beta(t+1)^2 + \gamma(t+1)] + a6^t + \beta t^2 + \gamma t = -6^t + t$$

$$25a6^t + 2\beta = -6^t + t$$

Again,  $\beta$  and  $\gamma$  remain undetermined.

# Discriminant $\Delta=0$

Try out an alternative guess function  $y_t^{g3}$  (multiplying the undetermined part of  $y_t^{g2}$  by  $t$ ):

$$y_t^{g3} = (a6^t) + (\beta t^3 + \gamma t^2)$$

$$y_{t+1}^{g3} = (a6^{t+1}) + (\beta(t+1)^3 + \gamma(t+1)^2)$$

$$y_{t+2}^{g3} = (a6^{t+2}) + (\beta(t+2)^3 + \gamma(t+2)^2)$$

Substituting in the non-homogeneous equation yields:

$$(a6^{t+2}) + (\beta(t+2)^3 + \gamma(t+2)^2) - 2[(a6^{t+1}) + (\beta(t+1)^3 + \gamma(t+1)^2)] + (a6^t) + (\beta t^3 + \gamma t^2) = -6^t + t \Leftrightarrow$$

$$25a6^t + 6\beta t + (6\beta + 2\gamma) = -6^t + t$$

Equating coefficient yields a unique solution for  $\beta$  and  $\gamma$  as well:

$$6\beta = 1 \wedge 6\beta + 2\gamma = 0$$

$$\beta = \frac{1}{6} \wedge \gamma = -\frac{1}{2}$$

Therefore:

$$PS : \bar{y}_t = -\frac{1}{25}6^t + \frac{1}{6}t^3 - \frac{1}{2}t^2$$

$$GS : y_t = A_1 + A_2t - \frac{1}{25}6^t + \frac{1}{6}t^3 - \frac{1}{2}t^2$$

# Complex numbers

The imaginary number  $i$  is defined solely by the property that its square is  $-1$ .

$$i^2 = -1$$

A complex number  $z$  is a number that can be expressed in the form:

$$z = a + bi$$

where  $a$  and  $b$  are real numbers, and  $i$  represents the imaginary unit, satisfying the equation  $i^2 = -1$ .

Real part:

$$\operatorname{Re}(a + bi) := a$$

Imaginary part:

$$\operatorname{Im}(a + bi) := b$$

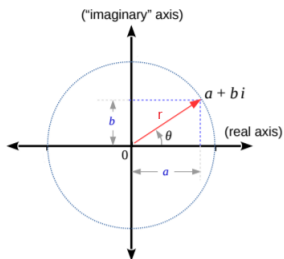
Complex conjugate:

$$\overline{a + bi} := a - bi$$

That is, negate the imaginary component.

# Complex numbers

The complex plane is a geometric representation of the complex numbers established by the real axis and the perpendicular imaginary axis.



Here  $r$  is the absolute value (or modulus or magnitude) of the complex number  $z$

$$r = \sqrt{a^2 + b^2}$$

and  $\theta$  the argument of  $z$

$$a = r \cos \theta \quad b = r \sin \theta$$



Solve  $y_{t+2} + 2y_{t+1} + 2y_t = 2^t$  assuming arbitrary initial conditions.  
Firstly consider the HE:

$$y_{t+2} + 2y_{t+1} + 2y_t = 0$$

$$y_{t+2} + a_1y_{t+1} + a_2y_t = 0$$

$$a_1 = 2, \quad a_2 = 2$$

while the necessary and sufficient conditions for stability, namely:

$$1 + a_1 + a_2 > 0$$

$$1 - a_2 > 0$$

$$1 - a_1 + a_2 > 0$$

are not simultaneously satisfied.

## Discriminant $\Delta < 0$

Moreover:

$$\lambda^2 + 2\lambda + 2y_t = 0$$

$$\Delta = (2)^2 - 4 \cdot 2 = -4 < 0$$

Since  $\Delta < 0$ , the roots of the characteristic equation are a complex conjugates:

$$\lambda_{1,2} = \frac{-2 \pm \sqrt{-4}}{2} = -1 \pm i$$

Cartesian coordinates:

$$(a, b) = (-1, 1)$$

The absolute value (or modulus or magnitude) of the complex number  $z = -1 + i$  is:

$$r = \sqrt{1^2 + 1^2} = \sqrt{2}$$

## Discriminant $\Delta < 0$

The argument of the complex number, denoted  $\arg(z)$  and labeled  $\theta$ :

$$a = r \cos \theta \Rightarrow -1 = \sqrt{2} \cos \theta \Rightarrow \cos \theta = \frac{-1}{\sqrt{2}}$$

$$b = r \sin \theta \Rightarrow 1 = \sqrt{2} \sin \theta \Rightarrow \sin \theta = \frac{1}{\sqrt{2}}$$

From the trigonometric tables we find that the angle whose sine is  $\frac{1}{\sqrt{2}}$  and whose cosine is  $\frac{-1}{\sqrt{2}}$ , is  $\frac{3\pi}{4}$ .

Therefore, the solution of the homogeneous equation is:

$$y_t = r^t (A_1 \cos \theta t + A_2 \sin \theta t) \Rightarrow y_t = \sqrt{2}^t (A_1 \cos(\frac{3\pi}{4} t) + A_2 \sin(\frac{3\pi}{4} t))$$

## Discriminant $\Delta < 0$

Next consider the non-homogeneous equation:

$$y_{t+2} + 2y_{t+1} + 2y_t = 2^t$$

Try out an exponential guess function:

$$y_t = a2^t, \quad y_{t+1} = a2^{t+1}, \quad y_{t+2} = a2^{t+2}$$

Substituting in the non-homogeneous equation:

$$a2^{t+2} + 2a2^{t+1} + 2a2^t = 2^t \Leftrightarrow (a2^2 + 2a2 + 2a)2^t = 2^t \Leftrightarrow 10a2^t = 2^t$$

$$10a = 1 \Leftrightarrow a = \frac{1}{10}$$

Therefore:

$$PS : \bar{y}_t = \frac{1}{10}2^t$$

$$GS : y_t = A_1\sqrt{2}^t \cos\left(\frac{3\pi}{4}t\right) + A_2\sqrt{2}^t \sin\left(\frac{3\pi}{4}t\right) + \frac{1}{10}2^t$$

# Operators

✓ Operator: A mapping of one set into another, each of which has a certain structure.

✓ For most practical purposes, operators can be treated just as algebraic quantities.

We introduce the lag operator  $L$  such that:

$$Ly_t = y_{t-1}$$

So,

$$L^2 y_t = y_{t-2}, L^n y_t = y_{t-n}, L^{-1} y_t = y_{t+1}$$

Formally, the operator  $L^n$  maps one sequence into another sequence.

Lag operator applied to a constant  $c$

$$Lc = c$$

Distributive

$$(L^j + L^i)y_t = y_{t-j} + y_{t-i}$$

Associative

$$L^j L^i y_t = L^i L^j y_t = L^{i+j} y_t = y_{t-i-j}$$

# Infinite-series expansions

Using a well-known infinite-series expansion , for  $|c| < 1$ , we have

$$\frac{1}{1-c} = 1 + c + c^2 + \dots = \sum_{i=0}^{\infty} c^i$$

Treating  $aL$  exactly like  $c$  we have that,

$$\frac{1}{(1-aL)} = (1-aL)^{-1} = 1 + aL + a^2L^2 + \dots = \sum_{i=0}^{\infty} a^i L^i$$

Notice that the above sequence is a bounded sequence if  $|a| < 1$ , but will divergent if  $|a| > 1$ . In this latter case, consider an alternative expansion:

$$(1-aL)^{-1} = - \sum_{i=1}^{\infty} \left(\frac{1}{a}\right)^i L^{-i}$$

# First-order Difference Equations

The general form is:

$$b_1 y_t + b_0 y_{t-1} = g(t)$$

- ✓ It may happen that we do not know the functional form of  $g(t)$ .
- ✓ We know the actual succession of values  $g(0), g(1), \dots, g(t)$ . In other words,  $g(t)$  is a sequence of known real values
- ✓ In such case the method of undetermined coefficients cannot be applied.
- ✓ It is possible to find a particular solution by applying operational methods.

# Backward and forward solutions

Solve:

$$b_1 y_t + b_0 y_{t-1} = x(t)$$

where  $x(t)$  is a sequence of known real values.

$$y_t + \frac{b_0}{b_1} y_{t-1} = \frac{x(t)}{b_1}$$

Setting  $b = \frac{b_0}{b_1}$  and  $X_t = \frac{x(t)}{b_1}$  we have:

$$y_t + b y_{t-1} = X_t$$

The solution of the homogeneous equation is:

$$y_t^h = c(-b)^t$$

where  $c$  is an arbitrary constant.



# Backward and forward solutions

Next, find a particular solution:

$$y_t + by_{t-1} = X_t$$

$$y_t + bLy_t = X_t$$

$$(1 + bL)y_t = X_t$$

If  $| -b | < 1$ , then the particular solution is:

$$\bar{y}_t = (1 - (-b)L)^{-1}X_t = \sum_{i=0}^{\infty} (-b)^i L^i X_t = \sum_{i=0}^{\infty} (-b)^i X_{t-i}$$

Note that  $\bar{y}_t$  is a bounded sequence if  $| -b | < 1$  (same:  $|b| < 1$ ) but will be divergent if  $| -b | > 1$ . In this latter case consider an alternative expansion.

$$\bar{y}_t = (1 - (-b)L)^{-1}X_t = - \sum_{i=1}^{\infty} \left(-\frac{1}{b}\right)^i L^{-i} X_t = - \sum_{i=1}^{\infty} \left(-\frac{1}{b}\right)^i X_{t+i}$$