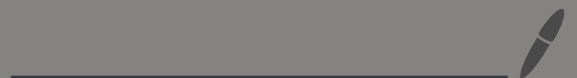


Lecture 3

- Further Examples-Function Spaces
- Metric Subspaces
- Open and Closed Balls



We move on with an important (in what follows) "category" of examples:

Example: X is a set of functions

For $V \neq \emptyset$ consider $B(V, \mathbb{R})$ and let

$d_{\text{sup}} : B(V, \mathbb{R}) \times B(V, \mathbb{R}) \rightarrow \mathbb{R}$ be defined

by: $f, g \in B(V, \mathbb{R}), d_{\text{sup}}(f, g) := \sup_{x \in V} |f(x) - g(x)|$

* d_{sup} is termed uniform metric

Notice that:

$$\begin{aligned} * \sup_{x \in V} |f(x) - g(x)| &\leq \sup_{x \in V} (|f(x)| + |g(x)|) \\ &\leq \sup_{x \in V} |f(x)| + \sup_{x \in V} |g(x)| < +\infty \end{aligned}$$

tr. ineq. for abs. value + addition of sup

$f, g \in B(V, \mathbb{R})$

Hence d_{sup} is a well defined real function.

* Obviously $\sup_{x \in V} |f(x) - g(x)| \geq 0 \quad \forall f, g$
hence p.d. holds ✓

* $0 = d_{\text{sup}}(f, g) \Leftrightarrow 0 = \sup_{x \in V} |f(x) - g(x)|$
 $\Leftrightarrow |f(x) - g(x)| = 0 \quad \forall x \in V \Leftrightarrow \underline{f(x) = g(x)} \quad \forall x \in V$

\Rightarrow $(f=g)$ hence separation holds

$$\begin{aligned} * \quad d_{\text{sup}}(g, f) &= \sup_{x \in Y} |g(x) - f(x)| = \sup_{x \in Y} |f(x) - g(x)| \\ &= d_{\text{sup}}(f, g), \text{ hence symmetry holds.} \end{aligned}$$

Symmetry of $|\cdot|$

* if $f, g, h \in BC(X, \mathbb{R})$

$$d_{\text{sup}}(f, g) = \sup_{x \in Y} |f(x) - g(x)| = \sup_{x \in Y} |f(x) + \underbrace{h(x)}_{\checkmark} - g(x)|$$

$$= \sup_{x \in Y} | \underbrace{(f(x) - h(x))}_{\checkmark} + \underbrace{(h(x) - g(x))}_{\checkmark} | \leq \sup_{x \in Y} [|f(x) - h(x)| +$$

$$+ |h(x) - g(x)|] \leq \sup_{x \in Y} |f(x) - h(x)| + \sup_{x \in Y} |h(x) - g(x)|$$

$= d_{\text{sup}}(f, h) + d_{\text{sup}}(h, g)$ hence the triangle inequality holds. \square

* The above is quite general and important in what follows. Some further sub-examples

arbitrary element of $\mathbb{R}^n \rightarrow \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$

* (Sub) - Example: It is possible to perceive (\mathbb{R}^n, d_{\max}) as a special case of $(B(V, \mathbb{R}), d_{\text{sup}})$ for a suitable choice of V :

- Let $V = \{1, 2, \dots, n\}$. A function $f: V \rightarrow \mathbb{R}$ can be represented by the n -vector $(f(1), f(2), \dots, f(n))$. Inversely if $(x_1, x_2, \dots, x_n) \in \mathbb{R}^n$

then it defines a function $f: V \rightarrow \mathbb{R}$ by $f(i) = x_i, i=1, \dots, n$. Hence there exists a bijective correspondence between $\{f: V \rightarrow \mathbb{R}\}$ and \mathbb{R}^n .

- Furthermore any $f: V \rightarrow \mathbb{R}$ is bounded since V is finite (remember the first lecture - its image in \mathbb{R} is finite). Hence $B(V, \mathbb{R}) \cong \mathbb{R}^n$.

- If $x, y \in \mathbb{R}^n$, $d_{\max}(x, y) = \max_{i=1, \dots, n} |x_i - y_i|$

$$= \max_{i=1, \dots, n} |f(i) - g(i)| = \max_{i \in X} |f(i) - g(i)|$$

max exists \Rightarrow equals \sup

$$= \sup_{i \in X} |f(i) - g(i)|$$

$$= d_{\sup}(f, g).$$

$f: Y \rightarrow \mathbb{R}$ represents x
 $g: Y \rightarrow \mathbb{R}$ represents Y

Hence d_{\max} "is essentially" d_{\sup} and thus

$$(\mathbb{R}^n, d_{\max}) \cong (B(\{1, 2, \dots, n\}, \mathbb{R}), d_{\sup})_{\mathbb{R}}$$

* (Sub-Example) - Bounded real sequences

- A real sequence is an "infinite dimensional vector,"

of the form $(x_0, x_1, \dots, x_n, \dots)$, $x_n \in \mathbb{R}, n \in \mathbb{N}$

\downarrow initial element
 \downarrow as many elements as the elements of \mathbb{N}
 \downarrow no final element

- eg. a. $(0, 1, 2, \dots, n, \dots)$ ✓
- b. $(1, 1/2, \dots, 1/n, \dots)$ ✓
- c. $(1, 1, 1, \dots, 1, \dots)$ ✓

- Equivalently a real sequence $(x_0, x_1, \dots, x_n, \dots)$

is represented by a function $f: \mathbb{N} \rightarrow \mathbb{R}$ since:

- $(x_0, x_1, \dots, x_n, \dots)$ defines $f: \mathbb{N} \rightarrow \mathbb{R}$ with

$$f(n) := x_n$$

- $f: \mathbb{N} \rightarrow \mathbb{R}$ defines the vector

$$(f(0), f(1), \dots, f(n), \dots)$$

a. $f(n) = n$, b. $f(n) = \frac{1}{n+1}$

- A real sequence is bounded iff the $f: \mathbb{N} \rightarrow \mathbb{R}$ that represents it is a bounded real function

$\Leftrightarrow \sup_{n \in \mathbb{N}} |f(n)| < +\infty \Leftrightarrow \sup_{n \in \mathbb{N}} |x_n| < +\infty$

1st lecture

a. $\sup_{n \in \mathbb{N}} |n| = +\infty$ not bounded

b. $\sup_{n \in \mathbb{N}} |1/(n+1)| = 1 < +\infty$ bounded.

- Hence $(B(\mathbb{N}, \mathbb{R}), d_{\text{sup}})$ is the space of bounded real sequences equipped with

the uniform metric.

e.g. c. $x_n = L \quad \forall n \in \mathbb{N}$ (L, L, \dots, L, \dots)

$f(n) = L \rightarrow$

$$\sup_{n \in \mathbb{N}} |x_n| = \sup_{n \in \mathbb{N}} L = L < +\infty$$

\rightarrow Constant sequence
at L

$\in B(\mathbb{N}, \mathbb{R})$

$$d_{\text{sup}} \left(\left(1, \frac{1}{2}, \dots, \frac{1}{n+1}, \dots \right), \left(L, L, \dots, L, \dots \right) \right)$$

$$= \sup_{n \in \mathbb{N}} \left| \frac{1}{n+1} - L \right| = \sup_{n \in \mathbb{N}} \left| \frac{1}{n+1} \right| = \sup_{n \in \mathbb{N}} \frac{1}{n+1}$$

why? $\lim_{n \rightarrow \infty} \frac{1}{n+1} = 0$

* (Sub)-Example

$V = [0, L]$, and consider $B([0, L], \mathbb{R})$.

Notice that $B([0, L], \mathbb{R}) \neq \emptyset$ since it contains the constant functions $f_c(x) = c, \forall x \in [0, L], c \in \mathbb{R}$.

Consider also $L > 0$, and the set

$$A_L := \{ f: [0, L] \rightarrow \mathbb{R} : f(0) = 0, \forall x, y \in [0, L] \\ |f(x) - f(y)| \leq L |x - y| \}$$

$$\left| \frac{\partial g}{\partial x}(x) \right| = \frac{L}{e} e^x$$

Notice that $A_L \neq \emptyset$ since for example

$$g(x) := \frac{L}{e} (e^x - 1) \in A_L :$$

$$g(0) = \frac{L}{e} (e^0 - 1) = 0$$

$$g(x) = g(y) + \frac{\partial g}{\partial x}(y^*) (x-y)$$

$$\Leftrightarrow g(x) - g(y) = \frac{\partial g}{\partial x}(y^*) (x-y)$$

y^* between x, y

if $x, y \in [0, 1]$, $|g(x) - g(y)| = \frac{L}{e} |e^x - e^y|$

$$\leq \frac{L}{e} \sup_{z \in [0, 1]} e^z |x-y| = \frac{L}{e} |x-y|$$

MVT $\frac{L}{e} \sup_{z \in [0, 1]} e^z$

$$|g(x) - g(y)|$$

$$= \left| \frac{\partial g}{\partial x}(y^*) \right| |y-x|$$

$$\leq \sup_{y^* \in [0, 1]} \frac{\left| \frac{\partial g}{\partial x}(y^*) \right|}{e} |y-x|$$

Furthermore if $f \in A_L$ we have that

$$\sup_{x \in [0, 1]} |f(x)| = \sup_{x \in [0, 1]} |f(x) - f(0)| \leq \sup_{x \in [0, 1]} L |x-0|$$

$$= L \sup_{x \in [0, 1]} |x| = L < \infty \text{ hence } f \in B([0, 1], \mathbb{R})$$

Thereby $\emptyset \neq A_L \subseteq B([0, 1], \mathbb{R})$

\hookrightarrow is an example of a uniformly Lipschitz set of functions

[to be defined ...]

Hence $B([0, 1], \mathbb{R})$ does not only contains constant

functions.

Another family of functions inside $B([0,1], \mathbb{R})$ is

$A_{\mathbb{N}} = \{ g_n = [0,1] \rightarrow \mathbb{R}, g_n(x) := nx, n \in \mathbb{N} \}$ since

$$\sup_{x \in [0,1]} |g_n(x)| = \sup_{x \in [0,1]} |nx| = \sup_{x \in [0,1]} nx = n \sup_{x \in [0,1]} x = n \cdot 1 = n$$

hence $g_n \in B([0,1], \mathbb{R}) \Rightarrow A_{\mathbb{N}} \subseteq B([0,1], \mathbb{R})$.

Exe. $d_{\text{sup}}(\frac{1}{e}(e^x-1), nx), \forall n \in \mathbb{N}$.

$(B([0,1], \mathbb{R}), d_{\text{sup}})$ is the resulting metric space when equipped with the uniform metric. \square

B. Metric Subspaces

Definition. Suppose that (X, d) is a metric space and $\emptyset \neq V \subseteq X$. Let d_V denote the restriction of d on $V \times V$ (i.e. consider d restricted only to pairs of elements of V). Obviously

d_V is a well-defined metric (why?) that can equip V , and the metric space (V, d_V) is termed a metric subspace of (X, d) .

Examples:

- (\mathbb{R}^n, d_{11}) , $V = \{x \in \mathbb{R}^n : x_i = 0 \text{ or } 1, \forall i=1, \dots, n\}$
 (obviously $V \subseteq \mathbb{R}^n$). if $x, y \in V$ then

$$d_{11}(x, y) = \sum_{i=1}^n |x_i - y_i| = \sum_{i=1}^n \begin{cases} 1, & x_i \neq y_i \\ 0, & x_i = y_i \end{cases}$$

$$= \# \{i=1, 2, \dots, n : x_i \neq y_i\} = d_H(x, y)$$

Hence when d_{11} is restricted on V it reduces to d_H . Thus (V, d_H) is a metric subspace

of (\mathbb{R}^n, d_{11}) [Does this hold for d_L, d_{\max} ?]

- (A_L, d_{sup}) , $(A_{\infty}, d_{\text{sup}})$ are metric subspaces of $(B([0, 1], \mathbb{R}), d_{\text{sup}})$.

$([0,1], d_u)$, $([0,1], d_e)$ are metric subspaces of (\mathbb{R}, d_u) and (\mathbb{R}, d_e) respectively.
 → abuse of notation

- etc. (we will see more examples as the course progresses)

[The notion of the Metric Subspace is an example of the construction of a metric space from a given one. We will later on see further examples, like product spaces, etc.]

C. Open and Closed Balls.

The notions of open and closed balls in a metric space is fundamental. It generalizes the notion of open and closed (bounded) intervals in \mathbb{R} , thus systems of such balls represent a lot of information about the metric space:

Definition: let (X, d) a metric space, $x \in X$ and $\varepsilon > 0$. The open ball of (X, d) centered at x , with radius ε is

$$O_d(x, \varepsilon) := \{ y \in X : d(x, y) < \varepsilon \}$$

Respectively the closed ball of (X, d) centered

at x with radius ε is

$$O_d[x, \varepsilon] := \{ y \in X : d(x, y) \leq \varepsilon \} \quad \square$$

* $\forall x \in X, \varepsilon > 0, x \in O_d(x, \varepsilon)$ and $x \in O_d[x, \varepsilon]$

since due to (2) $d(x, x) = 0 \leq \varepsilon$.

$\Rightarrow y \in O_d[x, \varepsilon]$

* if $y \in X$ and $d(x, y) < \varepsilon \Rightarrow d(x, y) \leq \varepsilon$ hence

$$\forall x \in X, \varepsilon > 0 \quad O_d(x, \varepsilon) \subseteq O_d[x, \varepsilon]$$

Not necessarily strict

* if $\delta > \varepsilon$ then if $d(x, y) < \varepsilon \Rightarrow d(x, y) < \delta$ hence

$$O_d(x, \varepsilon) \subseteq O_d(x, \delta)$$

Putting the above together, $\forall x \in X, \varepsilon, \delta > 0, \varepsilon < \delta$

* $O_d(x, \varepsilon) \subseteq O_d[x, \varepsilon] \subseteq O_d(x, \delta) \subseteq O_d[x, \delta]$

Not necessarily strict inclusions

Examples :

$$d_d(x, y) = \begin{cases} 0, & x=y \\ 1, & x \neq y \end{cases}$$

- (X, d_d) discrete space

We have that (why?)

$$O_d(x, \varepsilon) = \begin{cases} \{x\}, & \varepsilon \leq 1 \\ X, & \varepsilon > 1 \end{cases}$$

$$O_d[x, \varepsilon] = \begin{cases} \{x\}, & \varepsilon < 1 \\ X, & \varepsilon \geq 1 \end{cases}$$

→ A peculiar example - balls are either singletons or the whole space!

- (\mathbb{R}, d_u)

We have that

$$O_d(x, \varepsilon) = (x - \varepsilon, x + \varepsilon)$$

$$O_d[x, \varepsilon] = [x - \varepsilon, x + \varepsilon]$$

the "usual" intervals.

- (\mathbb{R}, d_e) [remember $d_e(x, y) = |e^x - e^y|$]

Notice that $d_e(x, y) \leq \varepsilon \Leftrightarrow |e^x - e^y| \leq \varepsilon \Leftrightarrow$

$$-\varepsilon \leq e^x - e^y \leq \varepsilon \Leftrightarrow e^x - \varepsilon \leq e^y \leq e^x + \varepsilon \checkmark$$

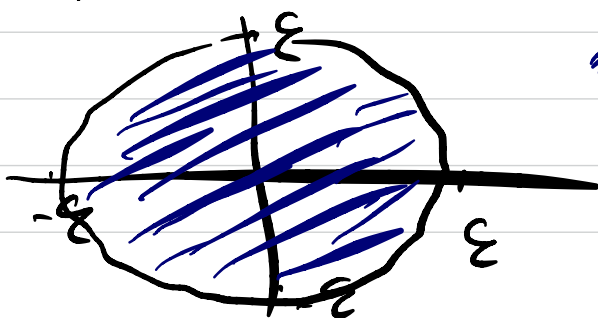
$$\Leftrightarrow y \in (k, \ln(e^x + \varepsilon)) \text{ with } k = \begin{cases} \ln(e^x - \varepsilon), & e^x > \varepsilon \\ -\infty, & e^x \leq \varepsilon \end{cases}$$

$$y \in [\ln(e^x - \varepsilon), \ln(e^x + \varepsilon)], k > -\infty$$

$$(-\infty, \ln(e^x + \varepsilon)], k = -\infty$$

Hence in (\mathbb{R}, d_e) intervals of the form $(-\infty, c)$ or $[\infty, c]$ are considered of finite radius something that is obviously not the case in (\mathbb{R}, d_u) .

- (\mathbb{R}^2, d_E) , $x = O_{2 \times 1}$, $\varepsilon > 0$

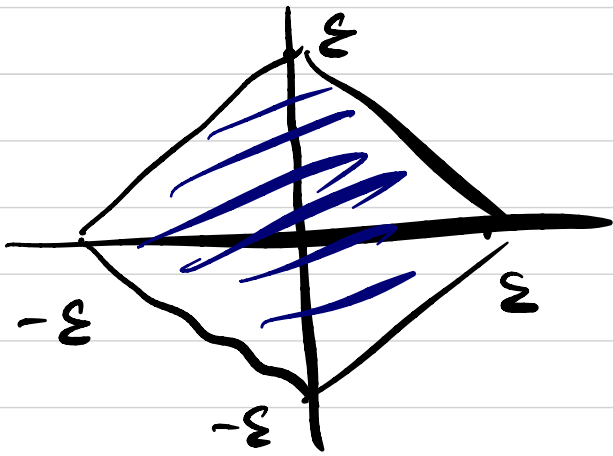


$$\equiv \equiv \equiv = \mathcal{O}_d(O_{2 \times 1}, \varepsilon)$$

$$\equiv \equiv \equiv \cup \emptyset = \mathcal{O}_d[\mathcal{O}_{2 \times 1}, \varepsilon]$$

- (\mathbb{R}^2, d_{11})

$$x = O_{2 \times 1}, \quad \varepsilon > 0$$

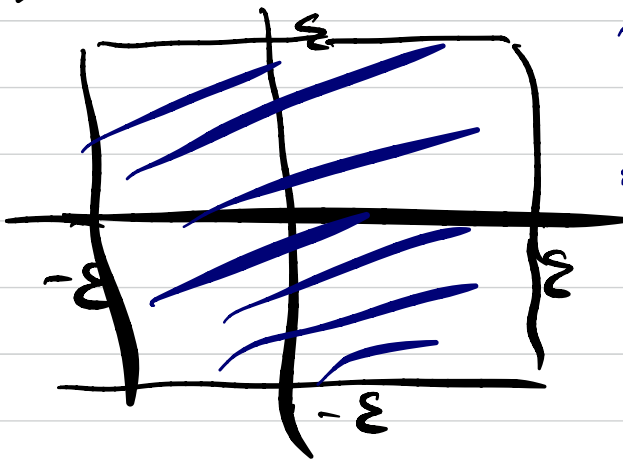


$$\equiv = \mathcal{O}_{d_{11}}(O_{2 \times 1}, \varepsilon)$$

$$\equiv \diamond = \mathcal{O}_{d_{11}}[O_{2 \times 1}, \varepsilon]$$

- (\mathbb{R}^2, d_{\max})

$$x = O_{2 \times 1}, \quad \varepsilon > 0$$



$$\equiv = \mathcal{O}_{d_{\max}}(O_{2 \times 1}, \varepsilon)$$

$$\equiv \square = \mathcal{O}_{d_{\max}}[O_{2 \times 1}, \varepsilon]$$

Hence different metrics can attribute different geometric objects as balls on the same carrier set.

Exercise: Consider $(B([0,1], \mathbb{R}), d_{\text{sup}})$. Let

$f(x) = L \quad \forall x \in [0,1]$. "Draw" $O_{d_{\text{sup}}}(f, L)$ and

$O_{d_{\text{sup}}}[f, L]$. \square

C.I. An initial property of Separation via Balls.

Lemma [Separation]. Let $x, y \in X$. Then $x \neq y$

$$\Leftrightarrow \exists \varepsilon_1, \varepsilon_2 > 0 : O_{d_{\text{sup}}}(x, \varepsilon_1) \cap O_{d_{\text{sup}}}(y, \varepsilon_2) = \emptyset.$$

Proof. (\Leftarrow) obvious from that $x \in O_{d_{\text{sup}}}(x, \varepsilon_1)$, $y \in O_{d_{\text{sup}}}(y, \varepsilon_2)$ and disjointness.

(\Rightarrow) $x \neq y \stackrel{(2)}{\Leftrightarrow} d(x, y) := \varepsilon > 0$. Let $\varepsilon_1 = \varepsilon_2 = \varepsilon/2$

Consider $O_{d_{\text{sup}}}(x, \varepsilon/2)$, $O_{d_{\text{sup}}}(y, \varepsilon/2)$ and suppose that

$z \in O_{d_{\text{sup}}}(x, \varepsilon/2) \cap O_{d_{\text{sup}}}(y, \varepsilon/2)$. Hence $d(x, z) < \varepsilon/2$ and

$d(y, z) < \varepsilon/2$. Then $\varepsilon = d(x, y) \stackrel{\text{tr. tri. + symmetry}}{\leq} \underbrace{d(x, z)}_{< \varepsilon/2} + \underbrace{d(y, z)}_{< \varepsilon/2} < \varepsilon/2 + \varepsilon/2 = \varepsilon$ impossible \square

Exercise: Does something analogous hold for closed balls? (obviously yes)

Hence balls separate points

[We could generalize in the obvious way the construction of balls for pseudo-metrics. Would such a separation result hold generally then?]

CII. Balls and dominance

Consider $(X, d_1), (X, d_2), x \in X, \varepsilon > 0$ and

$O_{d_1}(x, \varepsilon), O_{d_2}(x, \varepsilon)$. Suppose that $\exists c > 0$:

$d_1 \leq c d_2$ [functional inequality]

Let $y \in O_{d_2}(x, \varepsilon) \Leftrightarrow d_2(x, y) < \varepsilon \stackrel{c > 0}{\Leftrightarrow} c d_2(x, y) < c \varepsilon$

$\stackrel{\text{above}}{\Rightarrow} d_1(x, y) \in O_{d_1}(x, c\varepsilon) \Rightarrow O_{d_2}(x, \varepsilon) \subseteq O_{d_1}(x, c\varepsilon)$.

Hence $\forall x \in X, \varepsilon > 0, d_1 \leq c d_2 \Rightarrow O_{d_2}(x, \varepsilon) \subseteq O_{d_1}(x, c\varepsilon)$

Antitone transformation.

