

Lecture 07/04/20

Further details on boundness

1. $X, d_1, d_2, A \subseteq X, d_1 \leq c d_2, c > 0.$

If A is bounded w.r.t. d_2 then A is also bounded w.r.t. d_1 .

Corollary. Suppose that $\exists C_1, C_2 > 0: C_1 d_2 \leq d_1 \leq C_2 d_2 \quad (\star)$

(
- $d_1 \leq C^* d_2$ for
- $d_2 \leq C_* d_1, C^*, C_* > 0$)

then A is bounded w.r.t. d_1 iff

A is bounded w.r.t. d_2

(i.e. d_1, d_2 completely "agree" w.r.t. boundness)

E.g. $X = \mathbb{R}^d, d_1, d_{\max}, d_1$ and we know that every possible pair of them satisfies a relation of the previous type (\star) . Hence d_1, d_{\max}, d_1 completely "agree" w.r.t. boundness on \mathbb{R}^d .

2. Boundness and Metric Subspaces

Remember: i. (X, d) metric space, $A \subseteq X$

we can "restrict" d to A (obtaining d_A) hence

we obtain (A, d_A) as a metric subspace of the previous.

ii. $x \in A$, $\varepsilon > 0$, $O_{d_A}(x, \varepsilon) = O_d(x, \varepsilon) \cap A$
(something similar holds for closed balls)

iii. A is bounded iff $\exists x \in A, \varepsilon > 0$:
 $O_d(x, \varepsilon) \supseteq A$.

Lemma. (A, d_A) is bounded iff A is bounded w.r.t. d .

(It true it means that we may only consider the cases of whether a metric (sub-) space is bounded.)

Proof.

a. if (A, d_A) is bounded then A is a bounded subset of X .

b. if A is a bounded subset of X then (A, d_A) is bounded.

a. we know that (A, d_A) is bounded $\Leftrightarrow \exists x \in A, \varepsilon > 0$:

$O_{d_A}(x, \varepsilon) \supseteq A$ but we have that $O_{d_A}(x, \varepsilon) =$

$O_d(x, \varepsilon) \cap A \Rightarrow O_d(x, \varepsilon) \supseteq A \Leftrightarrow A$ is a bounded subset of X .

b. we know that A is a bounded subset of $X \Leftrightarrow$

$\exists x \in A, \varepsilon > 0$: $O_d(x, \varepsilon) \supseteq A$. Consider $O_{d_A}(x, \varepsilon) :=$

$O_d(x, \varepsilon) \cap A \supseteq A$. Hence (A, d_A) is bounded. \square

3. "Fragility of boundedness w.r.t. limit,"

Consider $X = \mathbb{R}$, for $n = 1, 2, 3, \dots$ Consider the \mathbb{N}^*

following $d_n: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, defined by:

$$x, y \in \mathbb{R}, \quad d_n(x, y) = \begin{cases} |x-y|, & |x-y| < n \\ n, & |x-y| \geq n \end{cases}$$

$$= \min(d_e(x, y), n) = \begin{cases} d_e(x, y), & d_e(x, y) < n \\ n, & d_e(x, y) \geq n \end{cases}$$

Exer. Show that d_n is a well defined metric for any $n = 1, 2, \dots$

(if $n=0$ was allowed, d_0 would be a pseudo-metric)

Hence we have essentially constructed a "sequence," of metric spaces, $(\mathbb{R}, d_1), (\mathbb{R}, d_2), (\mathbb{R}, d_3), \dots, (\mathbb{R}, d_n), \dots$

~~a. Consider \mathbb{R}, d_n , let $x \in \mathbb{R}$, and~~
bounded
Consider furthermore

$$\begin{aligned} \mathcal{O}_{d_n}(x, n+L) &= \{y \in \mathbb{R} : d_n(x, y) < n+L\} \\ &= \mathbb{R} \end{aligned}$$

Hence \mathbb{R} is bounded w.r.t. $d_n \forall n = 1, 2, \dots$

b. What happens to $d_n(x, y)$ as $n \rightarrow +\infty$?
fixed

We have that eventually (for large enough n)

$$d_n(x, y) = |x - y|, \text{ hence } \lim_{n \rightarrow \infty} d_n(x, y) = |x - y| = d(x, y)$$

Since x, y were arbitrary we have that

$$\forall x, y \in \mathbb{R} \quad d_n(x, y) \xrightarrow{n \rightarrow \infty} d(x, y)$$

(in some way - compare with the notion of pointwise convergence
- d_n converges to d)

Hence in some way \mathbb{R}, d is some kind of
limit of the previous sequence of metric space.

c. \mathbb{R}, d is not bounded

Hence we have an example for which boundedness is
"lost in the limit".

4. We have in many cases worked with $\underline{B(V, \mathbb{R})}$, d_{sup}

$$\{f: V \rightarrow \mathbb{R}, \text{ bounded}\}$$

- f is bounded $\Leftrightarrow f(V)$ is a bounded subset of \mathbb{R} w.r.t
 d_{e} .

$$d_{\text{sup}}(f, g) = \sup_{x \in X} |f(x) - g(x)| = \sup_{x \in X} d_{\text{e}}(f(x), g(x)).$$

We can now easily generalize the previous construction
Suppose that we have a metric space (X, d)

— $f: Y \rightarrow X$ will be considered bounded w.r.t. d
iff $f(Y)$ is a bounded subset of X w.r.t. d

i.e. $\exists z \in X, \varepsilon > 0: O_d(z, \varepsilon) \supseteq f(Y)$, hence

$B(Y, X)$ is well defined. (always $\neq \emptyset$ - constant functions)

— We can analogously define the analogue of d_{sup} in this extended setting:

$$f, g \in B(Y, X), \quad d_{\text{sup}}^*(f, g) = \sup_{x \in Y} d(f(x), g(x))$$

Exe. Show that d_{sup}^* is a well-defined metric.

5. (X, d) , $\varepsilon > 0$, $Z \subseteq X$. Consider the following collection of open balls:

$$O(Z, \varepsilon) = \left\{ O_d(x, \varepsilon), \forall x \in Z \right\}$$

The relevant collection of closed balls is

$$\bar{O}(Z, \varepsilon) = \left\{ O_d[x, \varepsilon], \forall x \in Z \right\}$$

When Z is finite then the collections above are termed finite.

When $A \subseteq X$, we say that A is covered by $\mathcal{O}(Z, \varepsilon)$ iff $\bigcup_{x \in Z} O_d(x, \varepsilon) \supseteq A$ (analogously for $\bar{\mathcal{O}}(Z, \varepsilon)$).

Theorem. A is bounded w.r.t. d iff $\exists \varepsilon > 0$ w.r.t. which there exists a finite $\mathcal{O}(Z, \varepsilon)$ that covers A .
[we can equivalently use closed balls - Exe!]

Proof. a. Suppose that A is bounded $\Rightarrow \exists x, \varepsilon > 0$:

$O_d(x, \varepsilon) \supseteq A$. Hence $\mathcal{O}(Z, \varepsilon) = \{O_d(x, \varepsilon)\}$,
 $Z = \{x\}$.

b. Suppose that there exists $\varepsilon > 0$ w.r.t. there exists a finite $\mathcal{O}(Z, \varepsilon)$ that covers A .

$\mathcal{O}(Z, \varepsilon)$ has the form $\{O_d(x_1, \varepsilon), O_d(x_2, \varepsilon), \dots, O_d(x_n, \varepsilon)\}$ for some $n \in \mathbb{N}^*$. ($Z = \{x_1, x_2, \dots, x_n\}$)

We will try to construct a "large enough" ball that covers $\bigcup_{i=1}^n O_d(x_i, \varepsilon)$. Without loss of generality choose x_1 as center.

$$\text{let } \delta := \max_{i=1, \dots, n} d(x_1, x_i) + \varepsilon + L > 0$$

$n \in \mathbb{N}^+ \Rightarrow$ this is well defined

We have that $O_d(x_1, \delta) \supseteq \bigcup_{i=1}^n O_d(x_i, \varepsilon)$, this is

due to that: let $y \in \bigcup_{i=1}^n O_d(x_i, \varepsilon) \Rightarrow y \in O_d(x_i, \varepsilon)$

for some i , that is $d(x_i, y) < \varepsilon$ for some i .

We have that $d(x_1, y) \leq d(x_1, x_i) + d(x_i, y) \leftarrow \varepsilon$

$$\leq \max_{i=1, \dots, n} d(x_1, x_i)$$

$$< \max_{i=1, \dots, n} d(x_1, x_i) + \varepsilon$$

$$< \max_{i=1, \dots, n} d(x_1, x_i) + \varepsilon + L = \delta$$

Hence $d(x_1, y) < \delta \Leftrightarrow y \in O_d(x_1, \delta) \Rightarrow$

$$O_d(x_1, \delta) \supseteq \bigcup_{i=1}^n O_d(x_i, \varepsilon) \supseteq A$$

hence $A \subseteq O_d(x_1, \delta)$ hence A is bounded. \square

Total Boundedness

Definition. A is totally bounded (w.r.t. d) iff $\forall \varepsilon > 0$

$\exists Z$ finite such that the collection

$O(z, \varepsilon)$ covers A .

[Dually we can consider collections of closed balls].

Remark. The definition allows the dependence of Z on ε . Hence both the centers and the cardinality of Z is allowed to change with ε .

Remark. When A is totally bounded then $\forall \varepsilon > 0$ Z can be chosen as a subset of A (i.e. the ball centers can be chosen to lie inside A).

Proof. Suppose that A is totally bounded. Let $\varepsilon > 0$.

Due to the previous for $\delta = \varepsilon/2$ there exists a finite Z such that the collection $\mathcal{O}(Z, \varepsilon/2)$ covers A . The collection $\mathcal{O}(Z, \varepsilon/2)$ is the set

of open balls $\{O_{\delta}(x_1, \varepsilon/2), O_{\delta}(x_2, \varepsilon/2), \dots, O_{\delta}(x_n, \varepsilon/2)\}$

($Z = \{x_1, x_2, \dots, x_n\}$ for n that may depend on $\varepsilon/2$).

If $Z \subseteq A$ then the collection $\mathcal{O}(Z, \varepsilon)$ covers A since

$O_{\delta}(x_i, \varepsilon/2) \subseteq O_{\delta}(x_i, \varepsilon) \quad \forall i = 1, \dots, n$. If $Z \not\subseteq A$ then:

Suppose that $x_1 \notin A$ without loss of generality.

Since $\bigcup_{i=1}^n O_d(x_i, \frac{\epsilon}{2}) \supseteq A$ we consider

$O_d(x_1, \frac{\epsilon}{2}) \cap A$. If this is empty then the ball

$O_d(x_1, \frac{\epsilon}{2})$ is not needed in the covering and thereby x_1 can be discarded from Z and we can move on to the next element of Z that does not lie in A .

So suppose that $O_d(x_1, \frac{\epsilon}{2}) \cap A$ is not empty.

Let $y \in O_d(x_1, \frac{\epsilon}{2})$. Consider $O_d(y, \epsilon)$. We have that if $z \in O_d(x_1, \frac{\epsilon}{2}) \cap A$ then $z \in O_d(y, \epsilon)$

We will continue it next time.

