An Example of a Metric based on Graph Structure Suppose that $V \neq \phi$ (set of vertice) and finite Definition. In unordered pair of elements of v is a see Exi, xy3 with x', xy EV. (Exi, xy3 is not actually a vector of elements of v, Since Exi, x13 = Ex1, x13, and this furtitions the term (unordered,) Definition. An unordered finite graph on V is a pair G= (V, E) where E is a collection of unordered quirs of elevents of V. [E is the set of edges in the Graph] E.g. $V = \{x_1, x_2, x_3\} \quad E = \{x_1, x_2\},$ $\{x_1, x_3\}$ • vertices 2trivial pocives $\{x_1, x_1\}$ ຸ Xາ • ×1, ×3 - elevents of E symmetric relations between the vertices Revark. Given the identification fx:, xy = = xy, xis, at most one edge can exist between any pair of vertices. Such graphs are called simple. Since G is simple and

V is finite, & must be also firste (why?), Such grapts (V finite and & finite) are called finite. Definition, If x,ye Y and Ex,y3 c & then x,y are called adjunce (connected by an edge Xary A path between Xy (Pxy) is a finite sequence in V -> essentially a vector why? (x, x, ..., xi, xin, ... Xn), with x=x, xn=y and Xiady Xin, ti=L..., n-L. Remark. A path is called a loop iff x=y. A loop is called trivial iff it is a singleton loop why do trivial loop exist, by the above?) Definition. A graph 6 is called connected, iff tx, ye V there exists a path Bry Levery vertex is reachable by any vertex via some porth) E.g. $V = \{x_1, x_2, x_3, x_4\}$ $f = \{\{x_1, x_3\}, \{x_1, x_3\}\}$ EX2, X37, EX2, X.3) ×, ×, ×, G= (N,E) connected E*= ?{X1,X1}, ?X1,X3}, ?X2,X3} (why?) 6x=(V,Ex) Not-connected (why?) ×, ×, ×,

- Some Algebra on Paths
- Transposition: if
$$P_{xs} = (x, x_{1}, ..., x_{n}, x_{n}, x_{n}, y)$$

then $P_{xy} = (y, x_{n+1}, ..., x_{in}, x_{i}, x_{i}, ..., x_{n}, x)$
Exe: $P_{xy} = P_{xy}$ iff P_{xy} is a trivial keep.
- Concatenation: if $P_{xy} = \sum x, x_{2}, ..., x_{i}, x_{inn}, ..., x_{n+1}, y_{3}$
and $P_{y/2} = iy$, $y_{2}, ..., y_{3}, y_{3+1}, ..., y_{n+1}, z_{3}$
then $P_{y/2} = i(x, x_{1}, ..., x_{i}, x_{inn}, ..., x_{n+1}, y_{3}, y_{3+1}, ..., y_{n+1}, z_{3})$
Concatenation: covers cut g ou conformable paths,
i.e. $P_{x,y} = P_{y,z}$ is definable iff $y=\infty$]
Exe: $(P_{x,x_{3}} - P_{y,z}) = P_{y,z} = P_{y,z} = P_{y,z}$
- dength of a path
Definition. If $P_{x,y}$ is a path definition for the sequence
Remains ..., H G is finite then the function length
assumes its values on IN (why?)
x_14 G is finite and connected then the
optimization $I_{xy} := Win S ength (P_{xy}), P_{xy}$ is a
path from x to y .

is well defined (it always produces a natural number) Since - G cometeted ∈) collection of paths from x,y ≠ \$\$, fxyev - G finite €) >> >> >> >> finite, fxyev (if Y was simply finite then it could be possible that Ix, y ∈ Y : $l_{x,y} = t\infty - why?$) From now on G will be simple, finite, and Connected: 3. Xxyer, long = ly x (why? use transposition) 4. Hx,y,zev, lx,y & lx,z + lz,y since lx, y < length (Px, z · Pz, y) Hos by construction by core. length (Px, z) + length (Pz, y) our optimal property and the < inequality above continuous to hold if 2,2 and 2,y in the inequality one chosen optimolly. E 5. lxy = 0 ift x=g (ushy?)

we are now ready to construct a lletric on v (not on 6) based on G. Netric voc G. det V≠ø, finite, and 6 a simple connected grouph on v dG: VXV-> IN, befined by $x,y\in V$, $d_{G}(x,y) := lx,y$ is a well defined Metric. - de is a well-defined function with values on IN by Ren. 9. - de cary = O (=) xay by Ren 5. - do is symmetric by Ren 3. - de satisfier the triangle incomolity by Real 4.

Remain, If V represents economic actors, and G interconnections between them w.r.f. optimal decisions, (e.g. local goures), dg could reflect the 1stroptegic interceptence, between the actors x,y in terms of their optimical decision making.