

1/4/2021 (1)

$$l^d = \alpha_0 - \alpha_1 \cdot (w-p) \quad (1)$$

$$l^s = b_0 + b_1 \cdot (w-p^e) \quad (2)$$

$$y^s = \delta \cdot l \quad (3)$$

$$y^d = \gamma_1 \cdot (y-T) - \gamma_2 \cdot [r - (p_{t+1}^e - p_t)] + \gamma_3 \cdot g \quad (4)$$

$$m - p = \delta_1 \cdot y - \delta_2 \cdot r \quad (5)$$

#### IV. Friedman-Phelps-Lucas Model

Στρέβλωση: Incomplete Information  
(Δεν είναι ομοίως + συμμετρική: ΑΤΕΛΗΣ)

Manliw (κεφ. 13): Workers **Misperception** Model (λειτουργία αυτών - εργατών)

↓  
Οι εργαζόμενοι δεν  
δυναμίζουν το  $p$ , αλλά  
έχουν μια εστίαση γι' αυτό  
 $p^e$

5 εξισώσεις + 5 άγνωστοι  
(1)-(5),  $y, l, r, p, w$

$$(1) : w-p = \frac{\alpha_0}{\alpha_1} - \frac{1}{\alpha_1} \cdot l^d \quad (1')$$

$$(2) : l^s = b_0 + b_1 \cdot (w-p^e) + b_1 \cdot p - b_1 \cdot p = b_0 + b_1 \cdot (w-p) + b_1 \cdot (p-p^e) \quad (2')$$

$$(1') \rightarrow (2') : l = b_0 + b_1 \cdot \left[ \frac{\alpha_0}{\alpha_1} - \frac{1}{\alpha_1} l \right] + b_1 \cdot (p-p^e) \Leftrightarrow$$

$$l^d = l^s = l \Leftrightarrow l \cdot \left[ 1 + \frac{b_1}{\alpha_1} \right] = b_0 + b_1 \cdot \frac{\alpha_0}{\alpha_1} + b_1 \cdot (p-p^e) \Leftrightarrow$$

1/4/2021 (2)

$$f^d = \alpha_0 - \alpha_1 \cdot (w - p) \quad (1)$$

$$f^s = \beta_0 + \beta_1 \cdot (w - p^e) \quad (2)$$

$$y^s = \delta \cdot l \quad (3)$$

$$\Leftrightarrow l = \frac{\alpha_1}{\alpha_1 + \beta_1} \cdot \frac{\alpha_1 \cdot \beta_0 + \beta_1 \cdot \alpha_0}{\alpha_1} + \frac{\beta_1 \cdot \alpha_1}{\alpha_1 + \beta_1} \cdot (p - p^e) \quad (4)$$

$$y^d = \gamma_1 \cdot (y - T) - \gamma_2 \cdot [r - (p_{t+1}^e - p_t^e)] + \gamma_3 \cdot g \quad (4)$$

Ισορροπία στις Αγορές Εργασίας

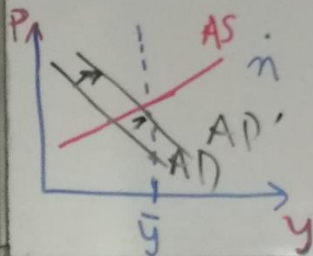
$$l = \frac{\alpha_1 \cdot \beta_0 + \beta_1 \cdot \alpha_0}{\alpha_1 + \beta_1} + \frac{\alpha_1 \cdot \beta_1}{\alpha_1 + \beta_1} \cdot (p - p^e) \quad (6)$$

$$m - p = \delta_1 \cdot y - \delta_2 \cdot r \quad (5)$$

(6) → (3)

**ΘΕΤΗ Κλίση AS**  
ΟΤΑΝ ΥΠΑΡΧΟΥΝ ΟΤΡΕΒΙΩΔΕΣ

$$AS: y = \delta \cdot \left[ \frac{\alpha_1 \cdot \beta_0 + \beta_1 \cdot \alpha_0}{\alpha_1 + \beta_1} \right] + \delta \cdot \frac{\alpha_1 \cdot \beta_1}{\alpha_1 + \beta_1} \cdot (p - p^e) \quad (7)$$



$$y = \bar{y} + \Gamma \cdot (p - p^e)$$

Av  $p - p^e > 0$  ( $p^e < p$ ),  $y > \bar{y}$   
 Av  $p - p^e < 0$  ( $p^e > p$ ),  $y < \bar{y}$

$$\Gamma = \frac{\delta \cdot \alpha_1 \cdot \beta_1}{\alpha_1 + \beta_1} > 0$$

Mankiw  
Sticky  
nominal  
wage

[Av  $p = p^e$ ,  $y = \bar{y}$ ]

1/4/2021 (3)

$$P^d = \alpha_0 - \alpha_1 \cdot (w - p) \quad (1)$$

$$P^s = \beta_0 + \beta_1 \cdot (w - p^e) \quad (2)$$

$$y^s = \delta \cdot l \quad (3)$$

Πως από AS →

$$y^d = \gamma_1 \cdot (y - T) - \gamma_2 \cdot [r - (p_{t+1}^e - p_t)] + \gamma_3 \cdot g \quad (4)$$

$$m - p = \delta_1 \cdot y - \delta_2 \cdot r \quad (5)$$

### IV. Friedman-Phelps-Lucas Model

Στρέβλωση: Incomplete Information

AS:  $y = \bar{y} + \Gamma \cdot (P - p^e)$   $\Gamma > 0$

Lucas Supply Curve

$$\Leftrightarrow (y - \bar{y}) = \Gamma \cdot (P - p^e)$$

$$= -\Gamma \cdot (p^e - P)$$

*note: σαν αριθμητικό πολλαπλασιαστή*

Καμωύν Phillips

$$y = \bar{y} + \Gamma \cdot (P - p^e) \Leftrightarrow$$

$$\Leftrightarrow y - \bar{y} = \Gamma \cdot (P - p^e) \Leftrightarrow$$

$$\Leftrightarrow P - p^e = \frac{1}{\Gamma} \cdot (y - \bar{y}) \Leftrightarrow$$

$C, P, y \rightarrow$  σε λογαριθμικούς  $P_t$ : *η τιμή της περιόδου*

$$\Leftrightarrow P = p^e + \frac{1}{\Gamma} \cdot (y - \bar{y}) \Leftrightarrow P - P_{-1} = p^e - p_{-1} + \frac{1}{\Gamma} \cdot (y - \bar{y}) \Leftrightarrow$$

$$\begin{matrix} P - P_{-1} = \pi \\ p^e - p_{-1} = \pi^e \end{matrix}$$

$$\Leftrightarrow \pi = \pi^e + \frac{1}{\Gamma} \cdot (y - \bar{y}) \Leftrightarrow$$

$$\left\{ \text{OKUN'S Law: } y - \bar{y} = -B \cdot (u - \bar{u}) \right\}$$

$\bar{u} \rightarrow$  φυσικό ποσοστό ανεργίας

$$\frac{1}{\Gamma} \cdot (y - \bar{y}) = -\frac{1}{\Gamma} \cdot B \cdot (u - \bar{u}) = -\Delta \cdot (u - \bar{u})$$

$$\Leftrightarrow \pi = \pi^e - \Delta \cdot (u - \bar{u}) \text{ ή}$$

$$\pi - \pi^e = -\Delta \cdot (u - \bar{u}) \text{ Καμωύν Phillips}$$