

ΕΣΤΩ ΤΩΡΑ $\text{COV}(\varepsilon_i, \varepsilon_j) \neq 0$ ←
 ΤΑ ΓΡΑΜΜΙΚΑ ΜΟΝΤΕΛΑ ΠΟΥ ΜΑΣ ΔΙΝΟΥΝ ΑΥΤΟ ΤΟ ΑΠΟΤΕΛ.
 ΕΙΝΑΙ ΤΑ

AR AUTOREGRESSIVE
 MA MOVING AVERAGE
 ARMA AUTOREGR. MOVING AVER.

AR(k)
 ↑ k IS THE ORDER OF AR MODEL

$$\varepsilon_t = \mu + \varphi_1 \varepsilon_{t-1} + \varphi_2 \varepsilon_{t-2} + \dots + \varphi_k \varepsilon_{t-k} + \eta_t$$

AR(1) $\varepsilon_t = \mu + \varphi \varepsilon_{t-1} + \eta_t$

$\eta_t \stackrel{iid}{\sim} (0, \sigma^2)$

ΑΥΤΟ ΠΟΥ ΘΕΛΟΥΜΕ ΑΠΟ ΜΙΑ ΣΤΟΧΑΣΤΙΚΗ
ΔΙΑΔΙΚΑΣΙΑ ΚΑΙ ΕΙΔΙΚΟΤΕΡΑ ΑΠΟ ΜΙΑ ΧΡΟΝΟΛΟΓΙΚΗ
ΣΕΙΡΑ, ΕΣΤΩ y_t , ΕΙΝΑΙ ΝΑ ΕΙΝΑΙ ΣΤΑΣΙΜΗ.
ΑΡΑ ΜΙΑ ΧΡΟΝΟΛ. ΣΕΙΡΑ y_t ΕΙΝΑΙ L^{ns} ΤΗ' f -ns
ΣΤΑΣΙΜΗ (L^{ns} ORDER STATIONARY) ANN

$E(y_t)$, $E(y_t^2)$ ΚΑΙ $\text{cov}(y_t, y_{t-k})$ ΕΙΝΑΙ
ΑΝΕΞΑΡΤΗΤΑ ΤΟΥ ΧΡΟΝΟΥ t .

ΑΥΤΟ' ΠΟΥ ΚΑΝΟΥΜΕ ΣΥΝΗΘΩΣ ΕΙΝΑΙ ΝΑ' ΘΑ' ΓΟΥΜΕ
ΠΡΟΡΙΘΜΟΥΣ ΓΩΙΣ ΠΑΡΕΚΤΕΡΟΥΣ ΩΣΤΕ

Η ΣΤΟΧΑΣΤΙΚΗ ΔΙΑΔΙΚΑΣΙΑ ΝΑ' ΕΙΝΑΙ ΣΤΑΣΙΜΗ ΩΣ ΤΑΞΗΣ

AR(1) ΕΙΝΑΙ ΣΤΑΘΕΡΟ AN $|q| < 1$

$$x_t = \mu + q x_{t-1} + u_t \quad u_t \stackrel{iid}{\sim} (0, \sigma^2)$$

$$E(x_t) = \mu + q E(x_{t-1}) + \underbrace{E(u_t)}_0$$

$$\Rightarrow E(x_t) = \mu + q E(x_{t-1})$$

if STATION.

$$\Rightarrow E(x_t)(1-q) = \mu \Rightarrow E(x_t) = \frac{\mu}{1-q}$$

$$V(x_t) = V(\mu + q x_{t-1} + u_t) =$$

$$\Rightarrow V(x_t) = V(q x_{t-1} + u_t) \Rightarrow$$

$$\Rightarrow V(x_t) = q^2 V(x_{t-1}) + V(u_t) + 2q \text{Cov}(x_{t-1}, u_t)$$

$$\Rightarrow V(x_t) = q^2 V(x_{t-1}) + \sigma^2 + 0$$

$\Rightarrow$ STATION. $V(\varepsilon_t) = \frac{\sigma^2}{1-\gamma^2}$

$$\begin{aligned}
 \varepsilon_t &= \mu + \gamma \varepsilon_{t-1} + u_t = \\
 &= \mu + \gamma \mu + \gamma^2 \varepsilon_{t-2} + u_t + \gamma u_{t-1}, \\
 &= \mu + \gamma \mu + \gamma^2 \mu + \gamma^3 \varepsilon_{t-3} + u_t + \gamma u_{t-1} + \gamma^2 \varepsilon_{t-2} \\
 &= \mu (1 + \gamma + \gamma^2 + \dots) + u_t + \gamma u_{t-1} + \gamma^2 u_{t-2} + \gamma^3 u_{t-3} + \dots
 \end{aligned}$$

$\Rightarrow E(\varepsilon_t) = \mu (1 + \gamma + \gamma^2 + \gamma^3 + \dots)$

$\Rightarrow E(\varepsilon_t) = \frac{\mu}{1-\gamma}$ iff $|\gamma| < 1$ ④

$$v(z_t) = V \left(h(1 + \zeta + \zeta^2 + \dots) + u_t + \zeta u_{t-1} + \zeta^2 u_{t-2} + \dots \right)$$

$$= V(u_t + \zeta u_{t-1} + \zeta^2 u_{t-2} + \zeta^3 u_{t-3} + \dots)$$

$$= V(u_t) + \zeta^2 V(u_{t-1}) + \zeta^4 V(u_{t-2}) + \zeta^6 V(u_{t-3}) + \dots$$

$$\Rightarrow V(z_t) = \sigma^2 (1 + \zeta^2 + \zeta^4 + \zeta^6 + \dots)$$

$$\Rightarrow V(z_t) = \underbrace{\sigma^2}_{1-\zeta^2} \stackrel{!A}{=} \zeta^2 < 1 \quad (B)$$

$$(A) + (B) \Rightarrow | \zeta | < 1$$

$$\gamma_k = \text{cov}(\varepsilon_t, \varepsilon_{t-k})$$

$$\gamma_1 = \text{cov}(\varepsilon_t, \varepsilon_{t-1})$$

$$\text{cov}(\varepsilon_{t+1}, \varepsilon_t) = \gamma_1$$

$$\varepsilon_t = \mu + \phi \varepsilon_{t-1} + u_t \rightarrow$$

$$\text{cov}(\varepsilon_t, \varepsilon_{t-k}) = \text{cov}(\mu + \phi \varepsilon_{t-1} + u_t, \varepsilon_{t-k})$$

$$\Rightarrow \gamma_k = \phi \text{cov}(\varepsilon_{t-1}, \varepsilon_{t-k}) + \text{cov}(u_t, \varepsilon_{t-k})$$

$$\Rightarrow \gamma_k = \phi \gamma_{k-1} + 0$$

$$\Rightarrow \gamma_k = \phi \gamma_{k-1}$$

$$\gamma_1 = \phi \gamma_0 = \phi \frac{\sigma^2}{1-\phi^2}$$

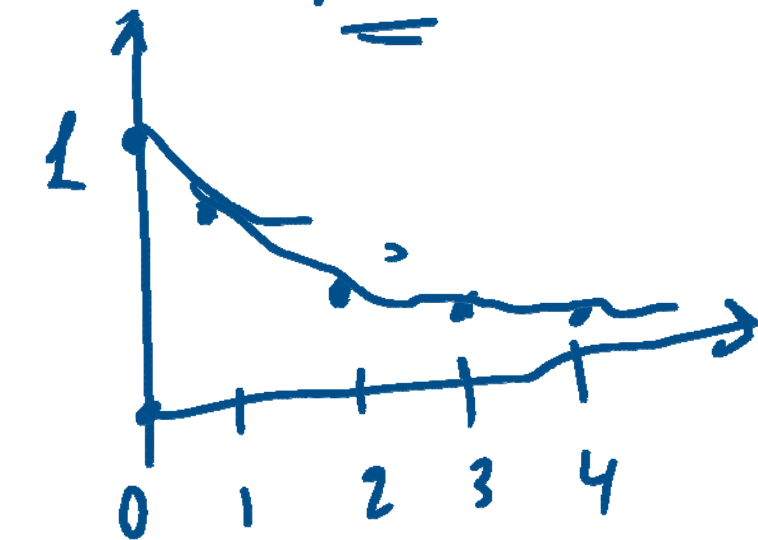
$$\gamma_2 = \phi \gamma_1 = \phi^2 \gamma_0$$

$\vdots$

$$\gamma_k = \phi^k \gamma_0$$

$$\rho_k = \frac{\gamma_k}{\gamma_0} = \phi^k \leftarrow$$

(AUTOCORRELATION
FUNCTION)
ACF



$\rho_k^\bullet$ = PARTIAL AUTOCOR. OF ORDER k

= AUTOCOR. ΤΩΝ ε_t ΜΕ ε_{t-k} ΑΦΟΨ
ΛΑΒΩΝ ΥΠ'ΟΨΗΝ ΜΟΝ ΤΑ AUTOCOR. ΤΩΝ
 $(\varepsilon_t, \varepsilon_{t-1}), (\varepsilon_t, \varepsilon_{t-2}), \dots, (\varepsilon_t, \varepsilon_{t-k+1})$

$$\varepsilon_t = C^* + \rho_k \varepsilon_{t-k} + v_t$$

$$\varepsilon_t = C^{**} + \delta_1 \varepsilon_{t-1} + \delta_2 \varepsilon_{t-2} + \dots + \delta_{k-1} \varepsilon_{t-k+1} + \rho_k^\bullet \varepsilon_{t-k} + v_t^*$$

$$\rho_1^* = \rho_1 = 4$$

$$\varepsilon_t = \mu + \gamma \varepsilon_{t-1} + \rho_2^* \varepsilon_{t-2} + u_t$$

$$\varepsilon_t \text{ ö60v } E^* \text{ @ } \varepsilon_t = \mu + \gamma \varepsilon_{t-1} + u_t \quad \Bigg| \Rightarrow$$

$$\Rightarrow \rho_2^* = 0 \sim \rho_3^* \sim \rho_4^* = \dots$$



ΕΣΤΩ ΤΩΡΑ ΟΤΙ ΤΑ ΛΑΘΗ ε_t ΑΚΟΝΟΙΟΥΝ ΑΡ(1)

$$\begin{pmatrix} y_t \\ 1 \times 1 \end{pmatrix} = \begin{pmatrix} x_t \beta \\ 1 \times K \quad K \times 1 \end{pmatrix} + \varepsilon_t$$

$$\varepsilon_t = \rho \varepsilon_{t-1} + u_t, \quad u_t \stackrel{iid}{\sim} (0, \sigma^2)$$

$$y = x\beta + \varepsilon \quad E(\varepsilon) = 0$$

$$n \times 1 \quad n \times K \quad K \times 1 \quad n \times 1$$

$$V(\varepsilon) = E(\varepsilon \varepsilon')$$

$$= E \begin{pmatrix} \varepsilon_1^2 & \varepsilon_1 \varepsilon_2 & \varepsilon_1 \varepsilon_3 & \dots & \varepsilon_1 \varepsilon_n \\ \varepsilon_2 \varepsilon_1 & \varepsilon_2^2 & \rho \varepsilon_2 \varepsilon_3 & \dots & \rho \varepsilon_2 \varepsilon_n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \varepsilon_n \varepsilon_1 & \varepsilon_n \varepsilon_2 & \dots & \dots & \varepsilon_n^2 \end{pmatrix} = \begin{pmatrix} \sigma_0 & \sigma_1 & \sigma_2 & \dots & \sigma_{n-1} \\ \sigma_1 & \sigma_0 & \sigma_1 & \dots & \sigma_{n-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_{n-1} & \dots & \dots & \dots & \sigma_0 \end{pmatrix} =$$

$$= \sigma_0 \begin{pmatrix} 1 & \rho_1 & \rho_2 & \dots & \rho_{n-1} \\ \rho_1 & 1 & \rho_1 & & \rho_{n-2} \\ \vdots & & & & \\ \rho_{n-1} & \rho_{n-1} & \dots & & 1 \end{pmatrix} =$$

$$= \frac{\sigma^2}{1-\rho^2} \begin{pmatrix} 1 & \rho & \rho^2 & \dots & \rho^{n-1} \\ \rho & 1 & \rho & \dots & \rho^{n-2} \\ \vdots & & & & \\ \rho^{n-1} & \rho^{n-1} & \dots & & 1 \end{pmatrix} = \sigma^2 \underline{Q}$$

$V(\hat{\beta}) \neq \sigma^2 I_n \Rightarrow \hat{\beta} = (X'X)^{-1}X'y$ is UNBIASED
BUT INEFFICIENT.

ΠΥΣΗ ΕΙΝΑΙ ΕΚΤΙΜΗΣΗ ΜΕ MAXIMUM LIKELIHOOD
ΕΣΤΟ

$$① y_t = x_t' \beta + \varepsilon_t$$

$$② \varepsilon_t = \rho \varepsilon_{t-1} + u_t$$

ΚΑΙ $u_t \stackrel{iid}{\sim} N(0, \sigma^2)$

ΑΝΤΙΚΑΘΙΣΤΟΝΤΑΣ ΤΟ ε_t ΟΖΩΝ (1) ΕΧΟΥΜΕ

$$y_t = x_t' \beta + \rho \varepsilon_{t-1} + u_t \text{ ΚΑΙ ΑΠΟ } ① \varepsilon_{t-1} = y_{t-1} - x_{t-1}' \beta$$

$$\Rightarrow y_t = x_t' \beta + \rho y_{t-1} - \rho x_{t-1}' \beta + \textcircled{u_t}$$

$$\Rightarrow ③ y_t - \rho y_{t-1} = (x_t' - \rho x_{t-1}') \beta + u_t$$

$$y_t = x_t' \beta + \phi y_{t-1} + u_t$$

$$u_t \overset{i.i.d.}{\sim} N(0, \sigma^2)$$

$$I_t = \{x_{t+1}, y_t, x_t, y_{t-1}, x_{t-1}, y_{t-2}, x_{t-2}, \dots\}$$

$$E(y_t | I_{t-1}) = x_t' \beta + \phi y_{t-1} - \phi x_{t-1}' \beta$$

$$V(y_t | I_{t-1}) = V(u_t) = \sigma^2$$

$$\ell(y_1, y_2, \dots, y_n, \beta, \sigma^2, \phi) =$$

$$= \sum_{t=1}^n \ell(y_t | I_{t-1}) = \sum_{t=1}^n -\frac{1}{2} \ln 2\pi - \frac{1}{2} \ln \sigma^2 - \frac{1}{2\sigma^2} (y_t - x_t' \beta - \phi y_{t-1} + \phi x_{t-1}' \beta)^2$$

ALTERNATIVELY WE COULD ASSUME an MA Model.

$$\varepsilon_t = \mu + u_t - \theta u_{t-1}, \quad \text{MA}(1)$$

$$E(\varepsilon_t) = \mu + 0 - \theta \cdot 0 = \mu \quad \forall \theta$$

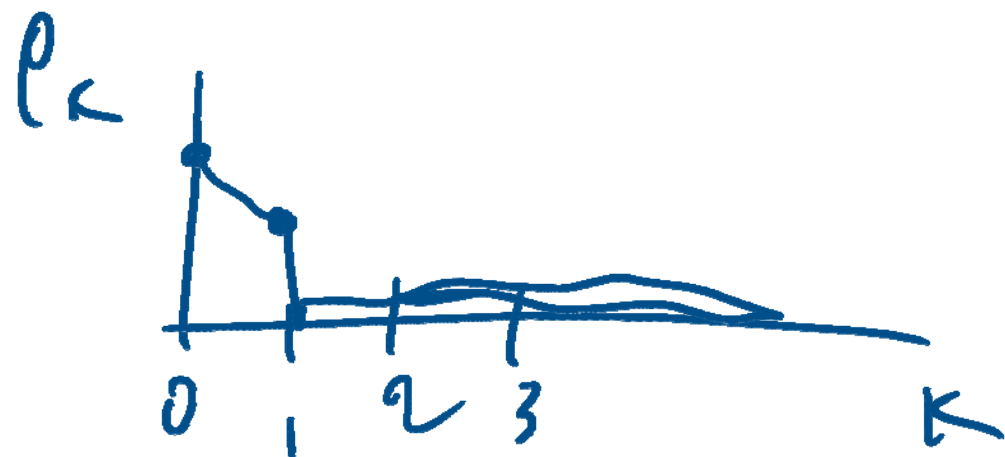
$$\begin{aligned} V(\varepsilon_t) &= V(\mu + u_t - \theta u_{t-1}) = V(u_t) + \theta^2 V(u_{t-1}) \\ &\quad - 2\theta \text{Cov}(u_t, u_{t-1}) = \sigma^2 + \sigma^2 \theta^2 - 0 = \end{aligned}$$

$$\Rightarrow V(\varepsilon_t) = \sigma^2 (1 + \theta^2) \quad \forall \theta,$$

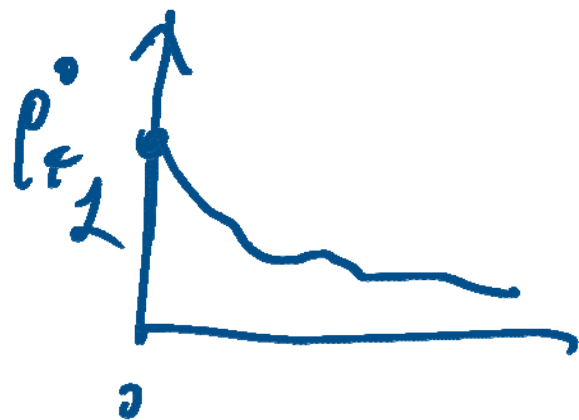
$\Rightarrow$ MA(1) ΠΑΝΤΑ ΣΤΑΣΙΜΟ ($\forall \theta$ is stationary σ^2 doesn't depend)

$$\text{Cov}(\varepsilon_t, \varepsilon_{t-k}) = \gamma_k = \begin{cases} -\frac{\theta}{(1+\theta^2)} \sigma^2 & k=1 \\ 0 & \forall k > 1 \end{cases}$$

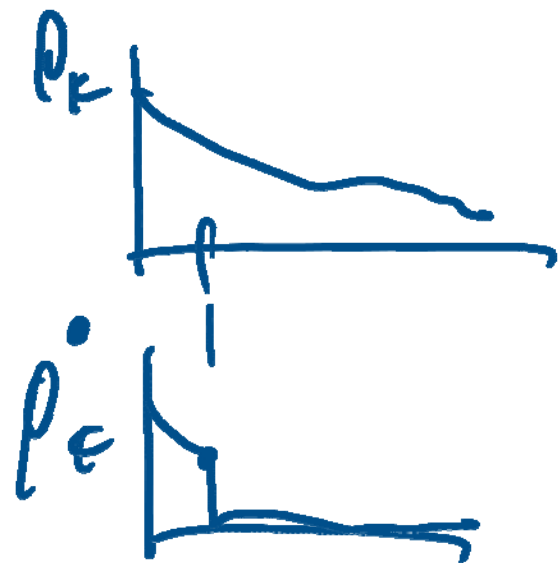
$$\rho_k = \begin{cases} -\frac{\partial}{1+\partial^2} & k=1 \\ 0 & k \geq 2 \end{cases}$$



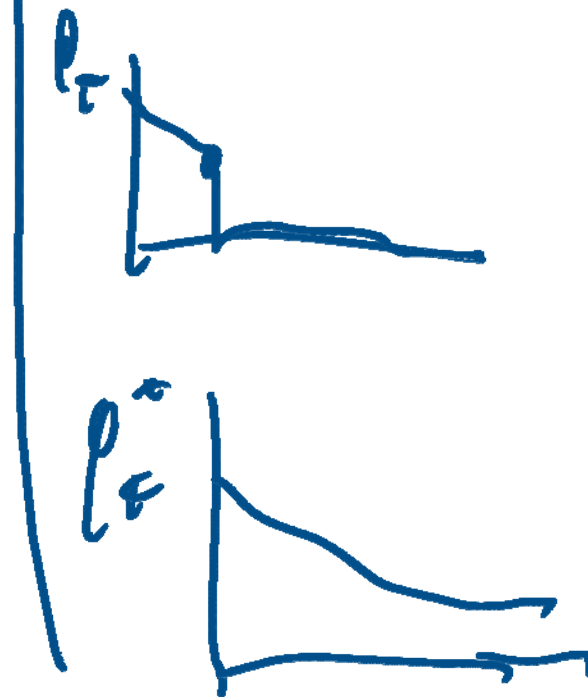
$$\rho_k^* = \partial^k \cdot \zeta_t$$



AR(1)

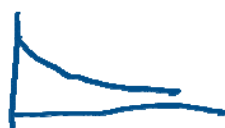


MA(1)



$ARMA(1,1)$ IS THE MIXED MODEL OF AR AND MA, i.e.

$$x_t = \mu + \phi x_{t-1} + \eta_t - \theta \eta_{t-1},$$

IN THIS CASE ρ_k 

and ρ_k^* 

AR(k), MA(k), ARMA(p, q)

ESTIMATION VIA MAX. LIKELIHOOD...

TESTING AUTOCOR.

$$H_0: \rho_K = 0 \text{ v.s. } H_1: \rho_K \neq 0$$

$$\hat{\rho}_K \underset{H_0}{\overset{A}{\sim}} N\left(0, \frac{1}{n}\right) \Leftrightarrow \sqrt{n} \hat{\rho}_K \underset{H_0}{\overset{A}{\sim}} N(0, 1)$$

reject H_0 iff

$$|\sqrt{n} \hat{\rho}_K| > 1.96 \quad (5\% \text{ size 2-sided})$$

$$\Rightarrow n \hat{\rho}_K^2 \underset{H_0}{\overset{A}{\sim}} \chi^2_1 \Rightarrow \text{reject } H_0 \text{ iff } n \hat{\rho}_K^2 > \chi^2_{1, 5\%}$$

As now $\hat{\rho}_i$ INDEPENDENT of $\hat{\rho}_j$ for $i \neq j$ we get:

$$Q_k = n(\hat{\rho}_1^2 + \hat{\rho}_2^2 + \dots + \hat{\rho}_k^2) \xrightarrow{H_0} \chi_k^2$$

$$H_0: \rho_1 = \rho_2 = \dots = \rho_k = 0 \quad \text{v.s.} \quad H_1: \text{At least one } \neq 0.$$

At least one $\neq 0$. Q_k is The BOX-Ljung test or PORTMANTEAU test

$$y_t = x_t' \hat{\beta} + \hat{\varepsilon}_t$$

LM-TEST

$$\hat{\varepsilon}_t = x_t' \delta + \alpha_1 \hat{\varepsilon}_{t-1} + \alpha_2 \hat{\varepsilon}_{t-2} + \dots + \alpha_k \hat{\varepsilon}_{t-k}$$

$\downarrow R^2$

nR^2

$$\xrightarrow{H_0} \chi_k^2$$

$$H_0: \alpha_1 = \alpha_2 = \dots = \alpha_k = 0$$

CONDITIONAL HETEROSKEDASTICITY

$$y_t = x_t' \beta + \varepsilon_t, \quad \varepsilon_t | I_{t-1} \sim N(0, \sigma_t^2)$$

$$\sigma_t^2 = \omega + \alpha \varepsilon_{t-1}^2$$

Autoregressive CONDITIONALLY
HETEROSKEDASTIC of order 1

ARCH(1)

$$I_{t-1} = \{ y_{t-1}, x_{t-1}, \dots \}$$
$$\sim \{ \varepsilon_{t-1}, \varepsilon_{t-2}, \dots \}$$

$$\sigma_t^2 = \omega + \alpha \varepsilon_{t-1}^2 \Rightarrow \varepsilon_t^2 = \omega + \alpha \varepsilon_{t-1}^2 + \underbrace{\varepsilon_t^2 - \sigma_t^2}_{v_t}$$

$$\Rightarrow \varepsilon_t^2 = \omega + \alpha \varepsilon_{t-1}^2 + v_t$$

$$\text{AR(1) of } \varepsilon_t^2 \quad \underline{\text{Assn}}$$

$$E(v_t) = 0$$

$$E(v_t v_{t-k}) = 0$$

$$E(\varepsilon_{t-1}^2 v_t) = 0$$

$$E(v_t) = E[E(v_t | I_{t-1})] =$$

$$= E[E(\varepsilon_t^2 - \sigma_t^2) | I_{t-1}] =$$

$$= E[E(\varepsilon_t^2 | I_{t-1}) - \sigma_t^2] = E(\bar{\sigma}_t^2 - \sigma_t^2) = 0$$

For $|\alpha| < 1 \Rightarrow E(\varepsilon_t^q) = w + \alpha E(\varepsilon_{t-1}^q) + E(v_t)$

$\Rightarrow E(\varepsilon_t^q)(1-\alpha) = w \Rightarrow E(\varepsilon_t^q) = \frac{w}{1-\alpha}$

$\sigma_t^q = w + \alpha \varepsilon_{t-1}^q$

POSITIVITY CONSTRAINTS.

CONSTRAINTS ON THE PARAMETERS of the
LGNOIT. VAR EQUATION such that

$P(\sigma_t^q > 0) = 1 \Leftrightarrow P(\sigma_t^q < 0) = 0$
for ARCH(1) $w > 0, \alpha \geq 0$

For σ_t^2 with POSIT. CONST. + STAT. INV.
 $\Rightarrow 0 \leq d < 1$

$$\sigma_t^2 = w + d \varepsilon_{t-1}^2$$

$$\sigma_t^2 = w + d_1 \varepsilon_{t-1}^2 + d_2 \varepsilon_{t-2}^2 + \dots + d_q \varepsilon_{t-q}^2$$

$$\text{ARCH}(q)$$

$$\sigma_t^2 = w + d \varepsilon_{t-1}^2 + \theta \sigma_{t-1}^2 \quad \sim \text{GARCH}(1,1)$$

$$\hookrightarrow \varepsilon_t^2 = w + (d + \theta) \varepsilon_{t-1}^2 + V_t - \theta V_{t-1}$$

$\text{ARMA}(1,1)$

ε_t^2 stationary iff $(\alpha + \theta) < 1$

$$\text{Corr}(\varepsilon_t^2, \varepsilon_{t-k}^2) = (\alpha + \theta)^{k-1} \rho_1$$

$$\rho_1 = \text{Corr}(\varepsilon_t^2, \varepsilon_{t-1}^2)$$

$\alpha + \theta = \text{PERSISTENCE}$

POSITIVITY CONSTRAINES

$$w > 0, \alpha \geq 0, \theta \geq 0$$

GARCH (2, 1)

$$\sigma_t^2 = \omega + b_1 \sigma_{t-1}^q + b_2 \sigma_{t-2}^L + \alpha \varepsilon_{t-1}^2$$

GARCH (1, 2)

$$\sigma_t^q = \omega + b \sigma_{t-1}^q + \alpha_1 \varepsilon_{t-1}^2 + \alpha_2 \varepsilon_{t-2}^2$$

GARCH (1, 1)

POSIT. CONST + station $\Rightarrow$

$$\omega > 0$$

$$\alpha > 0 \quad 0 \leq \alpha + b < 1$$

$$b \geq 0$$