

# 14/10/2020 Lecture

(Continue the proof of that when  $A$  is  $\epsilon$ -b., the ball centers of the collections that cover it can be chosen to lie inside  $A$ ,  $\forall \epsilon > 0$ ).

**Reminder:** For  $\epsilon > 0$ , we considered  $\sum_{i=1}^n O_d(x_i, \frac{\epsilon}{2})$  a finite cover of open balls of radius  $\frac{\epsilon}{2}$  that covers  $A$ .  
 $Z = \{x_1, x_2, \dots, x_n\}$ . We supposed that  $x_1 \notin A$ .

We considered the case  $O_d(x_1, \frac{\epsilon}{2}) \cap A$ .

We have chosen  $y \in O_d(x_1, \frac{\epsilon}{2}) \cap A$ , and considered the ball  $O_d(y, \epsilon)$ : we have that  $O_d(y, \epsilon) \supseteq O_d(x_1, \frac{\epsilon}{2}) \cap A$ .

This is due to that: if  $z \in O_d(x_1, \frac{\epsilon}{2}) \cap A$ , then

$$d(y, z) \leq d(x_1, y) + d(x_1, z) < \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon \Leftrightarrow$$

$$d(y, z) < \epsilon \Leftrightarrow z \in O_d(y, \epsilon) \Rightarrow O_d(y, \epsilon) \supseteq O_d(x_1, \frac{\epsilon}{2}) \cap A$$

Obviously we can repeat the previous procedure for any  $x_i \in Z$  such that  $x_i \notin A$ .

Hence for any  $x_i \in Z$  and  $x_i \notin A$ , and  $O_d(x_i, \frac{\epsilon}{2}) \cap A \neq \emptyset$ , we can find some  $y_i \in A$  such that  $O_d(y_i, \epsilon) \supseteq O_d(x_i, \frac{\epsilon}{2}) \cap A$ .

For each  $x_i \in Z$ , for which  $x_i \notin A$  we consider  $O_d(x_i, \epsilon)$ .

Obviously due to monotonicity we have that

$O_d(x_i, \varepsilon) \supseteq O_d(x_i, \varepsilon_k) \cap A$ . Hence we have constructed a finite collection of open balls of radius  $\varepsilon$  with:

- i. centers inside  $A$  and ii. the collection covers  $A$ .

The result follows since  $\varepsilon$  is arbitrary.  $\square$

**Lemma.** The previous hold if instead of covers by open balls we had considered covers of closed balls.

**Proof.** (covers of open balls  $\Rightarrow$  covers of closed balls)

Suppose  $A$  is t.b. (based on covers of open balls) and  $\varepsilon > 0$ . There exists a cover of open balls, say,

$$O_\varepsilon(A) = \{O_d(x_1, \varepsilon), O_d(x_2, \varepsilon), \dots, O_d(x_n, \varepsilon)\}$$

such that  $\bigcup_{i=1}^n O_d(x_i, \varepsilon) \supseteq A$ . We have that  $O_d(x_i, \varepsilon) \subseteq O_d[x_i, \varepsilon]$   $\forall i = 1, 2, \dots, n \Rightarrow \bigcup_{i=1}^n O_d[x_i, \varepsilon] \supseteq A$ . Hence

$$\{O_d[x_1, \varepsilon], O_d[x_2, \varepsilon], \dots, O_d[x_n, \varepsilon]\}$$
 is the required

collection. (Hence the definition of t.b. using open balls implies the definition of t.b. using closed balls)

(covers of closed balls  $\Rightarrow$  covers of open balls)

Suppose that  $A$  satisfies the definition of  $\epsilon$ -b.

w.r.t. covers of closed balls. Let  $\epsilon > 0$ : we know that there exists a <sup>finite</sup> collection of closed balls

$\{ \bar{O}_d[x_1, \epsilon/2], \bar{O}_d[x_2, \epsilon/2], \dots, \bar{O}_d[x_n, \epsilon/2] \}$  that covers

$A$ . We know that  $O_d(x_i, \epsilon) \supseteq \bar{O}_d[x_i, \epsilon/2] \forall i=1, \dots, n$

$\Rightarrow \bigcup_{i=1}^n O_d(x_i, \epsilon) \supseteq \bigcup_{i=1}^n \bar{O}_d[x_i, \epsilon/2] \supseteq A$  hence the

collection  $\{ O_d(x_1, \epsilon), O_d(x_2, \epsilon), \dots, O_d(x_n, \epsilon) \}$  is the required one. Since  $\epsilon$  is arbitrary the result follows.  $\square$

Further useful results:

•  $X, d$  will be considered totally bounded iff

$X$  is totally bounded w.r.t. as a subset of itself.

•  $A \subseteq X$  is totally bounded w.r.t.  $d$ , iff

$A, d_A$  is totally bounded (Proof - Exercise!).

Use the result on the choice of the ball centers - it is similar to the proof of the analogous result for boundedness).

**Lemma** If  $A$  is totally bounded w.r.t.  $d$  then

it is also bounded w.r.t.  $d$ .

Proof. [checks the definitions using the covers!]

Lemma. If  $A$  is finite then it is totally bounded. (this holds for any metric!)

Proof. If  $A = \emptyset$  then  $A$  is trivially t.b. Suppose that  $A \neq \emptyset$ , i.e. it is of the form

$$A = \{x_1, x_2, \dots, x_m\}, x_i \in X \quad \forall i=1, \dots, m$$

For  $\varepsilon > 0$ , consider  $\{O_d(x_1, \varepsilon), O_d(x_2, \varepsilon), \dots, O_d(x_m, \varepsilon)\}$

Since  $x_i \in O_d(x_i, \varepsilon) \quad \forall i=1, \dots, m$ , we have that

$$\bigcup_{i=1}^m O_d(x_i, \varepsilon) \supseteq A. \text{ Since } \varepsilon \text{ is arbitrary}$$

the result follows.  $\square$

Lemma. If  $A$  is t.b. w.r.t.  $d$  and  $B \subseteq A$  then  $B$  is also t.b. w.r.t.  $d$ .

Proof. If  $\varepsilon > 0$  the cover of open balls covers  $A$  it necessarily covers  $B$ .

Dually: if  $A$  is not t.b. w.r.t.  $d$  and  $B \supseteq A$  then also  $B$  is not t.b. w.r.t.  $d$

( $A$  is not t.b. iff  $\nexists \varepsilon > 0$ : every finite collection of open balls of radius  $\varepsilon$  cannot cover  $A$ ).

## Examples and Counter-examples

1.  $X, d_d$  ( $X, d_d$  is always bounded)

We will show that:  $X, d_d$  is totally bounded  
iff it is finite.

Proof a. (finite  $\Rightarrow$  t.b.)

(see above).

b. (if  $X, d_d$  is t.b. then it is finite).

Suppose that  $X$  is infinite. Let  $\varepsilon = 1/2$ .

(Reminder  $O_d(x, 1/2) = \{x\} \cup \{x \in X\}$ ). This directly

implies that the only way to cover  $X$   
by open balls of radius  $1/2$  is:

$$\bigcup_{x \in X} O_d(x, 1/2)$$

$$\bigcup \varepsilon x^3 = X$$

but the collection  $\{O_d(x, 1/2), x \in X\}^{x \in X}$  is not  
finite since  $X$  is infinite. The result follows.  $\square$

Hence the previous implies via example that total boundedness is strictly stronger than boundedness.

2. Is  $\mathbb{R}, d_u$  totally bounded? No since it is not even bounded. The same holds for  $\mathbb{R}^d, d_I$ .

(the interesting question here is when  $A \subseteq \mathbb{R}^d$  is t.b. w.r.t.  $d_I$ ).

3. Remember  $B(\mathbb{N}, \mathbb{R})$ ,  $d_{\sup}$  (bounded real sequences with the uniform metric).

$$A = \left\{ f_n \in B(\mathbb{N}, \mathbb{R}), f_n(n) = \begin{cases} 1 & n=n \\ 0 & n \neq n, n \in \mathbb{N} \end{cases} \right\}$$

Reminder: infinite dimensional vector representation of  $f_n$

$$(0, 0, \dots, \underbrace{1}_{(n+1)^{\text{th}} \text{ position}}, 0, \dots, 0, \dots)$$

E.g.  $f_0 \quad (1, 0, 0, \dots, 0, \dots)$

We have proven that  $A$  is bounded w.r.t.

$d_{\sup}$  (we have used uniform boundedness).

Is  $A$  totally bounded w.r.t.  $d_{\sup}$ ?  $A$  is not totally bounded due to that: we know that if  $A$  were t.b. then the centers of the covering balls can be chosen to belong to  $A$ .

Also we have that  $\underline{d_{\sup}}(f_n, f_m) = \begin{cases} 0, & n=m \\ 1, & n \neq m. \end{cases}$

$A$  is obviously infinite. For  $\varepsilon = \frac{1}{2}$

$\mathcal{O}_{d_{\sup}}(f_m, \frac{1}{2}) \cap A = \{f_m\}$ . Hence in order to be able to cover  $A$  with open balls

of the form  $\mathcal{O}_{d_{\sup}}(f_m, \frac{1}{2})$ ,  $m \in \mathbb{N}$  we need as many of those balls as there are elements of  $A$ . But  $A$  is infinite. Hence  $A$  is not totally bounded w.r.t.  $d_{\sup}$ .  $\square$

In order to construct examples the following notion will be useful:

## Covering Numbers and Metric Entropy.

We will use without loss of generality covers by closed balls.

Framework:  $X, d, A \subseteq X, \varepsilon > 0$

**Definition:** The covering number of  $A$  w.r.t.  $\varepsilon$  and  $d$ ,  $N(\varepsilon, d, A) := \min \#$  of closed balls of radius  $\varepsilon$  that

**Remark:** it is possible to prove that  $N(\varepsilon, d, A)$  is unique  $\forall \varepsilon, d, A$ .

•  $\ln N(\varepsilon, d, A)$  is the metric entropy number w.r.t.  $\varepsilon$  and  $d$ .

• It is easy to show that  $A$  is f.b. w.r.t.  $d$  iff  $N(\varepsilon, d, A) \in \mathbb{N}$  (i.e. it is  $<\infty$ )  $\forall \varepsilon > 0$ .

(dually  $A$  is not f.b. w.r.t.  $d$  iff  $\exists \varepsilon > 0$ :  $N(\varepsilon, d, A) = +\infty$ )

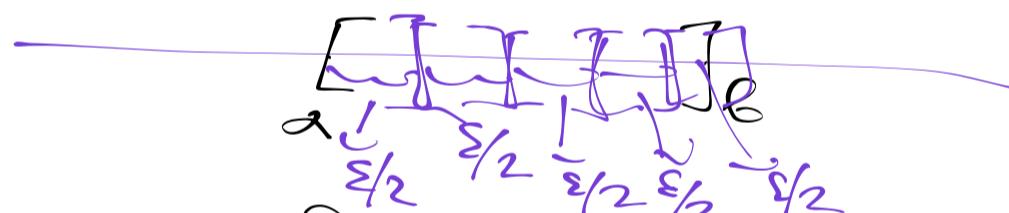
• It is easy to see that  $N(\varepsilon, d, A)$  is decreasing

w.r.t.  $\varepsilon$  for fixed  $d, A$ .

- Generally, as  $\varepsilon \downarrow 0$ ,  $N(\varepsilon, d, A) \rightarrow \infty$   
 $(\varepsilon \rightarrow 0)$  for fixed  $d, A$   
 Even when  $A$  is t.b.
- What is very informative on the complexity of  $A$  as a metric (sub-)space is the rate at which  $N(\varepsilon, d, A)$  (or equivalently  $\ln N(\varepsilon, d, A)$ ) diverges as  $\varepsilon \downarrow 0$ .

E.g.  $X = \mathbb{R}$ ,  $d = d_u$

$$[\alpha, \beta] = \bigcup_{\varepsilon} \left[ \frac{\alpha + \beta}{2}, \frac{\beta - \alpha}{2} \right]$$



$$N(\varepsilon, d_u, [\alpha, \beta]) = \begin{cases} 1, & \varepsilon \geq \frac{\beta - \alpha}{2} \\ \text{undefined}, & \varepsilon < \frac{\beta - \alpha}{2} \end{cases} \nearrow \infty$$

$\nexists \varepsilon > 0$ . Hence  $[\alpha, \beta]$  is t.b. w.r.t.  $d_u$

Hence we have shown that  $\forall x \in \mathbb{R}, \varepsilon > 0, O_{d_u}[x, \varepsilon]$  is totally bounded w.r.t.  $d_u$ . Hence if  $A \subseteq \mathbb{R}$  is bounded w.r.t.  $d_u$  then it is also t.b. w.r.t.  $d_u$ .

Hence Boundness  $\Leftrightarrow$  Total Boundedness inside  $\mathbb{R}, d_u$